



Some inequalities for $(s_1, m_1) - (s_2, m_2)$ -convex functions on the co-ordinates

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Abstract

In this paper, the authors introduce a new concept “ $(s_1, m_1) - (s_2, m_2)$ -convex function on co-ordinates” and establish some inequalities for $(s_1, m_1) - (s_2, m_2)$ -convex functions of 2-variables on the co-ordinates.

Keywords: co-ordinated convex function; $(s_1, m_1) - (s_2, m_2)$ -convex function; inequality.

1 Introduction

The following inequality, named after Simpson, is one of the best known results in the literature.

Theorem A. Let $f : I \subset \mathbb{R}_0 = [0, \infty) \rightarrow \mathbb{R} = (-\infty, \infty)$ be a four times continuously differentiable mapping on $[a, b]$ and $\|f^{(4)}\|_\infty = \sup_{x \in [a, b]} |f^{(4)}(x)| < \infty$. Then

$$\left| \frac{1}{6} \left[f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right] - \frac{1}{b-a} \int_a^b f(x) dx \right| \leq \frac{(b-a)^4}{2880} \|f^{(4)}\|_\infty. \quad (1.1)$$

For more information and recent development on Simpson's type inequalities, please refer to [1, 2, 3] and closely related references therein.

In [4], J. Park obtained the following generalized identity for some partial differentiable mappings on a bi-dimensional interval.

Lemma 1. Let $f : \Delta \rightarrow \mathbb{R}$ be a partial differentiable mapping on $\Delta = [a, b] \times [c, d] \subset \mathbb{R}^2$. If $\frac{\partial^2 f}{\partial t \partial \lambda} \in L(\Delta)$, then for

$r_1, r_2 \geq 2$ and $h_1, h_2 \in (0, 1)$ with $\frac{1}{r_1} \leq h_1 \leq \frac{r_1-1}{r_1}$, $\frac{1}{r_2} \leq h_2 \leq \frac{r_2-1}{r_2}$, we have

$$\begin{aligned} I(f)(h_1, h_2, r_1, r_2) &= \left[\frac{(r_1-2)(r_2-2)}{r_1 r_2} \right] f(h_1 a + (1-h_1)b, h_2 c + (1-h_2)d) \\ &+ \left[\frac{r_1-2}{r_1 r_2} \right] [f(h_1 a + (1-h_1)b, c) + f(h_1 a + (1-h_1)b, d)] + \left[\frac{r_2-2}{r_1 r_2} \right] [f(a, h_2 c + (1-h_2)d) + f(b, h_2 c + (1-h_2)d)] \\ &+ \frac{1}{r_1 r_2} [f(a, c) + f(a, d) + f(b, c) + f(b, d)] - \frac{1}{r_2(b-a)} \int_a^b [f(x, c) + (r_2-2)f(x, h_2 c + (1-h_2)d) + f(x, d)] dx \\ &- \frac{1}{r_1(d-c)} \int_c^d [f(a, y) + (r_1-2)f(h_1 a + (1-h_1)b, y) + f(b, y)] dy + \frac{1}{(b-a)(d-c)} \int_a^b \int_c^d f(x, y) dy dx \\ &= (b-a)(d-c) \int_0^1 \int_0^1 p(h_1, r_1, t) q(h_2, r_2, \lambda) \frac{\partial^2 f}{\partial t \partial \lambda}(ta + (1-t)b, \lambda c + (1-\lambda)d) dt d\lambda, \end{aligned}$$

where

$$p(h_1, r_1, t) = \begin{cases} t - \frac{1}{r_1}, & t \in [0, h_1] \\ t - \frac{r_1 - 1}{r_1}, & t \in [h_1, 1] \end{cases} \quad \text{and } q(h_2, r_2, \lambda) = \begin{cases} \lambda - \frac{1}{r_2}, & \lambda \in [0, h_2] \\ \lambda - \frac{r_2 - 1}{r_2}, & \lambda \in [h_2, 1]. \end{cases}$$

Moreover, J. Park established some Simpson-like type inequalities for co-ordinated s -convex mappings in the second sense.

The main purpose of this paper is to introduce the new concept “co-ordinated $(s_1, m_1) - (s_2, m_2)$ -convex function” and establish some new inequalities for such kind of functions on the co-ordinates.

2 Co-ordinated $(s_1, m_1) - (s_2, m_2)$ -convex functions

In [2, 4-10], Dragomir et al. and Park considered among others the class of mappings which are convex and s -convex on the co-ordinates.

Let us now consider a bi-dimensional interval $\Delta = [a, b] \times [c, d]$ in \mathbb{R}^2 with $b > a$ and $d > c$.

Definition 1. ([8]) A mapping $f : \Delta \rightarrow \mathbb{R}$ is said to be convex on Δ if the inequality

$$f(\alpha x + (1-\alpha)z, \alpha y + (1-\alpha)w) \leq \alpha f(x, y) + (1-\alpha)f(z, w)$$

holds for all $(x, y), (z, w) \in \Delta$ and $\alpha \in [0, 1]$. If the inequality is reversed, then f is said to be concave on Δ .

A modification for convex functions, which is also known as co-ordinated convex functions, was introduced by Dragomir in [6] as follows.

Definition 2. A function $f : \Delta \rightarrow \mathbb{R}$ is said to be convex on the co-ordinates on Δ if the partial mappings $f_y : [a, b] \rightarrow \mathbb{R}, f_y(u) = f(u, y)$ and $f_x : [c, d] \rightarrow \mathbb{R}, f_x(v) = f(x, v)$ are convex for all $x \in [a, b]$ and $y \in [c, d]$.

A formal definition for co-ordinated convex functions may be stated as follows.

Definition 3. A function $f : \Delta \rightarrow \mathbb{R}$ is said to be convex on the co-ordinates on Δ if the inequality

$$f(tx + (1-t)z, \lambda y + (1-\lambda)w) \leq t\lambda f(x, y) + t(1-\lambda)f(x, w) + \lambda(1-t)f(z, y) + (1-t)(1-\lambda)f(z, w)$$

holds for all $(x, y), (z, w), (x, w), (z, y) \in \Delta$ and $t, \lambda \in [0, 1]$.

Clearly, every convex mapping $f : \Delta \rightarrow \mathbb{R}$ is convex on the co-ordinates. Furthermore, there exists co-ordinated convex functions which are not convex. See [9].

Definition 4 ([4, 8, 10]) For the bi-dimensional interval $\Delta = [a, b] \times [c, d]$ in $\mathbb{R}_0^2 = [0, \infty)^2$ with $a < b$ and $c < d$, a mapping $f : \Delta \rightarrow \mathbb{R}$ is said to be s -convex on Δ if the inequality

$$f(\alpha x + (1-\alpha)z, \alpha y + (1-\alpha)w) \leq \alpha^s f(x, y) + (1-\alpha)^s f(z, w)$$

holds for all $(x, y), (z, w) \in \Delta$ and $\alpha \in [0, 1]$ and for some fixed $s \in (0, 1]$.

Definition 5. ([4, 8]) A function $f : \Delta = [a, b] \times [c, d] \subseteq \mathbb{R}_0^2 \rightarrow \mathbb{R}$ is called \mathbf{S} -convex on co-ordinates on Δ if the partial mappings $f_y : [a, b] \rightarrow \mathbb{R}, f_y(u) = f(u, y)$ and $f_x : [c, d] \rightarrow \mathbb{R}, f_x(v) = f(x, v)$ are s -convex for all $x \in [a, b], y \in [c, d]$ and $s \in (0, 1]$, i.e., f_y and f_x are s -convex for some fixed $s \in (0, 1]$.

Theorem B. ([8]) Every s -convex mapping $f : \Delta = [a, b] \times [c, d] \subseteq \mathbb{R}_0^2 \rightarrow \mathbb{R}$ is \mathbf{S} -convex on the co-ordinates. But, the converse is not true in general.

A formal definition for co-ordinated s -convex mappings may be stated as follow.

Definition 6. ([4,8]) A mapping $f : \Delta \rightarrow \mathbb{R}$ is called \mathbf{S} -convex on the co-ordinates on Δ if the inequality

$f(tx + (1-t)z, \lambda y + (1-\lambda)w) \leq t^s \lambda^s f(x, y) + t^s (1-\lambda)^s f(x, w) + \lambda^s (1-t)^s f(z, y) + (1-t)^s (1-\lambda)^s f(z, w)$
 holds for all $(x, y), (z, w), (x, w), (z, y) \in \Delta$ and $t, \lambda \in [0, 1]$ and $s \in (0, 1]$.

J. Park gave the notions of (s, m) -convexity and (s, m) -convexity on the co-ordinates for the function f on a rectangle from the plane \mathbb{R}^2 as follows.

Definition 7 ([11]). A mapping $f : \Delta_0 = [0, b] \times [0, d] \subset \mathbb{R}_0^2 \rightarrow \mathbb{R}$ is (s, m) -convex on Δ if the inequality
 $f(\alpha x + (1-\alpha)z, \alpha y + m(1-\alpha)w) \leq \alpha^s f(x, y) + m(1-\alpha^s) f(z, w)$
 holds for all $(x, y), (z, w) \in \Delta$ and $\alpha \in [0, 1]$ and for some fixed $s, m \in (0, 1]$.

Definition 8 ([11]). A function $f : \Delta_0 = [0, b] \times [0, d] \subset \mathbb{R}_0^2 \rightarrow \mathbb{R}$ is called (s, m) -convex on co-ordinates on Δ if the partial mappings $f_y : [0, b] \rightarrow \mathbb{R}, f_y(u) = f(u, y)$ and $f_x : [0, d] \rightarrow \mathbb{R}, f_x(v) = f(x, v)$ are (s, m) -convex for all $x \in [0, b], y \in [0, d]$ and $s, m \in (0, 1]$, i.e., f_y and f_x are (s, m) -convex with some fixed $s, m \in (0, 1]$.

Motivated by the above definitions, we now introduce the $(s_1, m_1) - (s_2, m_2)$ -convexity on the co-ordinates for a function $f(x)$ on a rectangle from the plane \mathbb{R}^2 as follows:

Definition 9. A function $f : \Delta_0 = [0, b] \times [0, d] \subset \mathbb{R}_0^2 \rightarrow \mathbb{R}$ is called $(s_1, m_1) - (s_2, m_2)$ convex on co-ordinates on Δ if the inequality
 $f(tx + m_1(1-t)z, \lambda y + m_2(1-\lambda)w)$
 $\leq t^{s_1} \lambda^{s_2} f(x, y) + m_1 t^{s_1} (1-\lambda^{s_2}) f(x, w) + m_2 \lambda^{s_2} (1-t^{s_1}) f(z, y) + m_1 m_2 (1-t^{s_1})(1-\lambda^{s_2}) f(z, w)$
 holds for all $(x, y), (z, w), (x, w), (z, y) \in \Delta$ with $t, \lambda \in [0, 1]$ and $s_1, s_2, m_1, m_2 \in (0, 1]$.

3 Some inequalities for $(s_1, m_1) - (s_2, m_2)$ -convex functions

Theorem 1 Let $f : \mathbb{R}_0^2 \rightarrow \mathbb{R}$ be a partial differentiable mapping on $\Delta_m = [0, \frac{b}{m_1}] \times [0, \frac{d}{m_2}]$ for $b > a > 0$ and $d > c > 0$.

If $\frac{\partial^2 f}{\partial t \partial \lambda} \in L(\Delta_m)$ is a co-ordinated $(s_1, m_1) - (s_2, m_2)$ -convex mapping on Δ_m for $s_1, s_2, m_1, m_2 \in (0, 1]$, then for

$r_1, r_2 \geq 2$ and $h_1, h_2 \in (0, 1)$ with $\frac{1}{r_1} \leq h_1 \leq \frac{r_1-1}{r_1}, \frac{1}{r_2} \leq h_2 \leq \frac{r_2-1}{r_2}$, the inequality

$$\frac{1}{(b-a)(d-c)} |I(f)(h_1, h_2, r_1, r_2)| \leq \mu(h_1, r_1, s_1) \left\{ \mu(h_2, r_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda}(a, c) \right| + m_2 \nu(h_2, r_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda}\left(a, \frac{d}{m_2}\right) \right| \right\} \\ + \nu(h_1, r_1, s_1) \left\{ m_1 \mu(h_2, r_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda}\left(\frac{b}{m_1}, c\right) \right| + m_1 m_2 \nu(h_2, r_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda}\left(\frac{b}{m_1}, \frac{d}{m_2}\right) \right| \right\}, \quad (3.1)$$

where

$$\mu(h, r, s) = M(r, s) + N(h, s), \quad \nu(h, r, s) = W(h, r) - M(r, s) - N(1-h, s),$$

and

$$M(r, s) = \frac{2 + 2(r-1)^{s+2} + r^{s+1}(s-r+2)}{(s+1)(s+2)r^{s+2}}, \quad N(h, s) = \frac{h^{s+1}((2h-1)s + 2(h-1))}{(s+1)(s+2)},$$

$$W(h, r) = \frac{1}{2} - h + h^2 + \frac{(2-r)}{r^2}.$$

Proof. From Lemma 1 and the co-ordinated $(s_1, m_1) - (s_2, m_2)$ -convexity of $\frac{\partial^2 f}{\partial t \partial \lambda}$, we have

$$\begin{aligned}
 & \frac{1}{(b-a)(d-c)} |I(f)(h_1, h_2, r_1, r_2)| \\
 & \leq \int_0^1 \int_0^1 |p(h_1, r_1, t)q(h_2, r_2, \lambda)| \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(ta + m_1(1-t) \frac{b}{m_1}, \lambda c + m_2(1-\lambda) \frac{d}{m_2} \right) \right| dt d\lambda \\
 & \leq \int_0^1 \int_0^1 |p(h_1, r_1, t)q(h_2, r_2, \lambda)| \left\{ t^{s_1} \lambda^{s_2} \left| \frac{\partial^2 f}{\partial t \partial \lambda} (a, c) \right| + m_1 t^{s_1} (1-\lambda^{s_2}) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(a, \frac{d}{m_2} \right) \right| \right. \\
 & \quad \left. + m_1(1-t^{s_1}) \lambda^{s_2} \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, c \right) \right| + m_1 m_2 (1-t^{s_1})(1-\lambda^{s_2}) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, \frac{d}{m_2} \right) \right| \right\} dt d\lambda \\
 & = \left(\int_0^1 |p(h_1, r_1, t)| t^{s_1} dt \right) \left\{ \left(\int_0^1 |q(h_2, r_2, \lambda)| \lambda^{s_2} d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} (a, c) \right| \right. \\
 & \quad \left. + m_2 \left(\int_0^1 |q(h_2, r_2, \lambda)| (1-\lambda^{s_2}) d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(a, \frac{d}{m_2} \right) \right| \right\} \\
 & \quad + \left(\int_0^1 |p(h_1, r_1, t)| (1-t^{s_1}) dt \right) \left\{ m_1 \left(\int_0^1 |q(h_2, r_2, \lambda)| \lambda^{s_2} d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, c \right) \right| \right. \\
 & \quad \left. + m_1 m_2 \left(\int_0^1 |q(h_2, r_2, \lambda)| (1-\lambda^{s_2}) d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, \frac{d}{m_2} \right) \right| \right\}. \tag{3.2}
 \end{aligned}$$

Note that

$$\begin{aligned}
 \int_0^1 |p(h_1, r_1, t)| t^{s_1} dt &= \mu(h_1, r_1, s_1); \quad \int_0^1 |q(h_2, r_2, \lambda)| \lambda^{s_2} dt = \mu(h_2, r_2, s_2); \\
 \int_0^1 |p(h_1, r_1, t)| dt &= \frac{1}{2} - h_1 + h_1^2 + \frac{(2-r_1)}{r_1^2} = W(h_1, r_1); \\
 \int_0^1 |q(h_2, r_2, t)| dt &= \frac{1}{2} - h_2 + h_2^2 + \frac{(2-r_2)}{r_2^2} = W(h_2, r_2); \\
 \int_0^1 |p(h_1, r_1, t)| (1-t^{s_1}) dt &= \int_0^1 |p(h_1, r_1, t)| dt - \int_0^1 |p(h_1, r_1, t)| t^{s_1} dt = W(h_1, r_1) - \mu(h_1, r_1, s_1); \\
 \int_0^1 |q(h_2, r_2, \lambda)| (1-\lambda^{s_2}) dt &= W(h_2, r_2) - \mu(h_2, r_2, s_2).
 \end{aligned}$$

Substituting the above equations into (3.2) and rearranging leads to (3.1). This completes the proof.

Corollary 1. Under the conditions of Theorem 1,

(i) if we choose $h_1 = h_2 = \frac{1}{2}$, $r_1 = r_2 = 6$, and $s_1 = s_2 = m_1 = m_2 = 1$ in (3.1), then

$$\left| I(f) \left(\frac{1}{2}, \frac{1}{2}, 6, 6 \right) \right| \leq \left(\frac{5}{72} \right)^2 M (b-a)(d-c).$$

(ii) if we choose $h_1 = h_2 = \frac{1}{2}$, $r_1 = r_2 = 2$, and $s_1 = s_2 = m_1 = m_2 = 1$ in (3.1), then

$$\left| I(f) \left(\frac{1}{2}, \frac{1}{2}, 2, 2 \right) \right| \leq \left(\frac{1}{8} \right)^2 M (b-a)(d-c),$$

where

$$M = \left| \frac{\partial^2 f}{\partial t \partial \lambda} (a, c) \right| + \left| \frac{\partial^2 f}{\partial t \partial \lambda} (a, d) \right| + \left| \frac{\partial^2 f}{\partial t \partial \lambda} (b, c) \right| + \left| \frac{\partial^2 f}{\partial t \partial \lambda} (b, d) \right|.$$

Theorem 2 Let $f : \mathbb{R}_0^2 \rightarrow \mathbb{R}$ be a partial differentiable mapping on $\Delta_m = [0, \frac{b}{m_1}] \times [0, \frac{d}{m_2}]$ for $b > a > 0$ and $d > c > 0$.

If $\square \left| \frac{\partial^2 f}{\partial t \partial \lambda} \right|^q \in L(\Delta_m)$ is a co-ordinated $(s_1, m_1) - (s_2, m_2)$ -convex mapping, where $s_1, s_2, m_1, m_2 \in (0, 1]$ and

$\frac{1}{p} + \frac{1}{q} = 1$ for $q > 1$, then for $r_1, r_2 \geq 2$ and $h_1, h_2 \in (0, 1)$ with $\frac{1}{r_1} \leq h_1 \leq \frac{r_1 - 1}{r_1}, \frac{1}{r_2} \leq h_2 \leq \frac{r_2 - 1}{r_2}$, the inequality

$$\frac{1}{(b-a)(d-c)} |I(f)(h_1, h_2, r_1, r_2)| \leq \mu_3^{\frac{1}{p}} \nu_3^{\frac{1}{q}} \left\{ \frac{1}{(s_1+1)(s_2+1)} \left[\left| \frac{\partial^2 f}{\partial t \partial \lambda} (a, c) \right|^q + m_2 s_2 \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(a, \frac{d}{m_2} \right) \right|^q + m_1 s_1 \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, c \right) \right|^q + m_1 s_1 m_2 s_2 \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, \frac{d}{m_2} \right) \right|^q \right] \right\}^{\frac{1}{q}} \quad (3.3)$$

is true, where

$$\mu_3 = \frac{2 + (r_1 - r_1 h_1 - 1)^{p+1} + (r_1 h_1 - 1)^{p+1}}{r_1^{p+1} (p+1)} \quad \text{and} \quad \nu_3 = \frac{2 + (r_2 - r_2 h_2 - 1)^{p+1} + (r_2 h_2 - 1)^{p+1}}{r_2^{p+1} (p+1)}.$$

Proof. From Lemma 1, we have

$$\begin{aligned} & \frac{1}{(b-a)(d-c)} |I(f)(h_1, h_2, r_1, r_2)| \\ & \leq \int_0^1 \int_0^1 |p(h_1, r_1, t) q(h_2, r_2, \lambda)| \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(ta + m_1(1-t) \frac{b}{m_1}, \lambda c + m_2(1-\lambda) \frac{d}{m_2} \right) \right| dt d\lambda \\ & \leq \left\{ \int_0^1 \int_0^1 |p(h_1, r_1, t) q(h_2, r_2, \lambda)|^p dt d\lambda \right\}^{\frac{1}{p}} \left\{ \int_0^1 \int_0^1 \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(ta + m_1(1-t) \frac{b}{m_1}, \lambda c + m_2(1-\lambda) \frac{d}{m_2} \right) \right|^q dt d\lambda \right\}^{\frac{1}{q}}. \end{aligned} \quad (3.4)$$

Hence, by the inequality (3.4) and the co-ordinated $(s_1, m_1) - (s_2, m_2)$ -convexity of $\left| \frac{\partial^2 f}{\partial t \partial \lambda} \right|^q$, it follows that

$$\begin{aligned} \frac{1}{(b-a)(d-c)} |I(f)(h_1, h_2, r_1, r_2)| & \leq \left\{ \int_0^1 \int_0^1 |p(h_1, r_1, t) q(h_2, r_2, \lambda)|^p dt d\lambda \right\}^{\frac{1}{p}} \left\{ \frac{1}{(s_1+1)(s_2+1)} \left[\left| \frac{\partial^2 f}{\partial t \partial \lambda} (a, c) \right|^q + m_2 s_2 \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(a, \frac{d}{m_2} \right) \right|^q + m_1 s_1 \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, c \right) \right|^q + m_1 m_2 s_1 s_2 \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{b}{m_1}, \frac{d}{m_2} \right) \right|^q \right] \right\}^{\frac{1}{q}}. \end{aligned}$$

Note that

$$\int_0^1 |p(h_1, r_1, t)|^p dt = \frac{2 + (r_1 - r_1 h_1 - 1)^{p+1} + (r_1 h_1 - 1)^{p+1}}{r_1^{p+1} (p+1)}$$

and

$$\int_0^1 |q(h_2, r_2, \lambda)|^p dt = \frac{2 + (r_2 - r_2 h_2 - 1)^{p+1} + (r_2 h_2 - 1)^{p+1}}{r_2^{p+1} (p+1)}.$$

Substituting the above equations into (3.4) and simplifying results in (3.3). The proof is complete.

Corollary 2 Under the conditions of Theorem 2,

(i) if we choose $h_1 = h_2 = \frac{1}{2}$, $r_1 = r_2 = 6$, and $s_1 = s_2 = m_1 = m_2 = 1$, then

$$\left| I(f) \left(\frac{1}{2}, \frac{1}{2}, 6, 6 \right) \right| \leq \left[\frac{2(1+2^{p+1})}{6^{p+1} (p+1)} \right]^{\frac{2}{p}} (b-a)(d-c) M_q^{\frac{1}{q}}.$$

(ii) if we choose $\mathbf{h}_1 = \mathbf{h}_2 = \frac{1}{2}, \mathbf{r}_1 = \mathbf{r}_2 = 2$, and $s_1 = s_2 = \mathbf{m}_1 = \mathbf{m}_2 = 1$, then

$$\left| \mathbf{I}(\mathbf{f})\left(\frac{1}{2}, \frac{1}{2}, 2, 2\right) \right| \leq \left[\frac{1}{2^p(p+1)} \right]^{\frac{2}{p}} (\mathbf{b} - \mathbf{a})(\mathbf{d} - \mathbf{c}) \mathbf{M}_q^{\frac{1}{q}}.$$

(iii) if we choose $\mathbf{h}_1 = \mathbf{h}_2 = \frac{1}{2}, \mathbf{r}_1 = \mathbf{r}_2 = 6$, $s_1 = s_2 = \mathbf{m}_1 = \mathbf{m}_2 = 1$, and $p = 1$, then

$$\left| \mathbf{I}(\mathbf{f})\left(\frac{1}{2}, \frac{1}{2}, 6, 6\right) \right| \leq \left(\frac{5}{36}\right)^2 (\mathbf{b} - \mathbf{a})(\mathbf{d} - \mathbf{c}) \mathbf{M}_q^{\frac{1}{q}},$$

where

$$\mathbf{M}_q = \frac{1}{4} \left(\left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{a}, \mathbf{c}) \right|^q + \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{a}, \mathbf{d}) \right|^q + \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{b}, \mathbf{c}) \right|^q + \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{b}, \mathbf{d}) \right|^q \right).$$

Theorem 3 Let $\mathbf{f} : \mathbb{R}_0^2 \rightarrow \mathbb{R}$ be a partial differentiable mapping on $\Delta_m = [0, \frac{\mathbf{b}}{m_1}] \times [0, \frac{\mathbf{d}}{m_2}]$ for $\mathbf{b} > \mathbf{a} > 0$ and $\mathbf{d} > \mathbf{c} > 0$.

If $\square \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}} \right|^q \in \mathbf{L}(\Delta_m)$ is a co-ordinated $(s_1, \mathbf{m}_1) - (s_2, \mathbf{m}_2)$ -convex mapping for $s_1, s_2, \mathbf{m}_1, \mathbf{m}_2 \in (0, 1]$, $q > 1$, and

$\frac{1}{p} + \frac{1}{q} = 1$, then, for $\mathbf{r}_1, \mathbf{r}_2 \geq 2$ and $\mathbf{h}_1, \mathbf{h}_2 \in (0, 1)$ with $\frac{1}{\mathbf{r}_1} \leq \mathbf{h}_1 \leq \frac{\mathbf{r}_1 - 1}{\mathbf{r}_1}, \frac{1}{\mathbf{r}_2} \leq \mathbf{h}_2 \leq \frac{\mathbf{r}_2 - 1}{\mathbf{r}_2}$, the inequality

$$\begin{aligned} \frac{1}{(\mathbf{b} - \mathbf{a})(\mathbf{d} - \mathbf{c})} |\mathbf{I}(\mathbf{f})(\mathbf{h}_1, \mathbf{h}_2, \mathbf{r}_1, \mathbf{r}_2)| &\leq \left\{ \left(\frac{1}{2} - \mathbf{h}_1 + \mathbf{h}_1^2 + \frac{(2 - \mathbf{r}_1)}{\mathbf{r}_1^2} \right) \left(\frac{1}{2} - \mathbf{h}_2 + \mathbf{h}_2^2 + \frac{(2 - \mathbf{r}_2)}{\mathbf{r}_2^2} \right) \right\}^{1 - \frac{1}{q}} \\ &\times \left\{ \boldsymbol{\mu}(\mathbf{h}_1, \mathbf{r}_1, s_1) \left[\boldsymbol{\mu}(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{a}, \mathbf{c}) \right|^q + m_2 \boldsymbol{\nu}(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}\left(\mathbf{a}, \frac{\mathbf{d}}{m_2}\right) \right|^q \right] \right. \\ &\left. + \boldsymbol{\nu}(\mathbf{h}_1, \mathbf{r}_1, s_1) \left[m_1 \boldsymbol{\mu}(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}\left(\frac{\mathbf{b}}{m_1}, \mathbf{c}\right) \right|^q + m_1 m_2 \boldsymbol{\nu}(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}\left(\frac{\mathbf{b}}{m_1}, \frac{\mathbf{d}}{m_2}\right) \right|^q \right] \right\}^{\frac{1}{q}}. \end{aligned} \tag{3.5}$$

holds true, where $\boldsymbol{\mu}$ and $\boldsymbol{\nu}$ are given in Theorem 2.1.

Proof. From Lemma 1, it follows that

$$\begin{aligned} \frac{1}{(\mathbf{b} - \mathbf{a})(\mathbf{d} - \mathbf{c})} |\mathbf{I}(\mathbf{f})(\mathbf{h}_1, \mathbf{h}_2, \mathbf{r}_1, \mathbf{r}_2)| &\leq \int_0^1 \int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t) q(\mathbf{h}_2, \mathbf{r}_2, \boldsymbol{\lambda})| \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{t}\mathbf{a} + (1 - t)\mathbf{b}, \boldsymbol{\lambda}\mathbf{c} + (1 - \boldsymbol{\lambda})\mathbf{d}) \right| dt d\boldsymbol{\lambda} \\ &\leq \left\{ \int_0^1 \int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t) q(\mathbf{h}_2, \mathbf{r}_2, \boldsymbol{\lambda})| dt d\boldsymbol{\lambda} \right\}^{1 - \frac{1}{q}} \left\{ \int_0^1 \int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t) q(\mathbf{h}_2, \mathbf{r}_2, \boldsymbol{\lambda})| \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{t}\mathbf{a} + (1 - t)\mathbf{b}, \boldsymbol{\lambda}\mathbf{c} + (1 - \boldsymbol{\lambda})\mathbf{d}) \right|^q dt d\boldsymbol{\lambda} \right\}^{\frac{1}{q}}. \end{aligned} \tag{3.6}$$

It is straightforward that

$$\int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t)| dt = \frac{1}{2} - \mathbf{h}_1 + \mathbf{h}_1^2 + \frac{(2 - \mathbf{r}_1)}{\mathbf{r}_1^2}, \int_0^1 |q(\mathbf{h}_2, \mathbf{r}_2, \boldsymbol{\lambda})| d\boldsymbol{\lambda} = \frac{1}{2} - \mathbf{h}_2 + \mathbf{h}_2^2 + \frac{(2 - \mathbf{r}_2)}{\mathbf{r}_2^2}.$$

Since $\left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}} \right|^q$ is a co-ordinated $(s_1, \mathbf{m}_1) - (s_2, \mathbf{m}_2)$ -convex mapping on Δ , we have

$$\begin{aligned} &\int_0^1 \int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t) q(\mathbf{h}_2, \mathbf{r}_2, \boldsymbol{\lambda})| \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{t}\mathbf{a} + (1 - t)\mathbf{b}, \boldsymbol{\lambda}\mathbf{c} + (1 - \boldsymbol{\lambda})\mathbf{d}) \right|^q dt d\boldsymbol{\lambda} \\ &\leq \int_0^1 \int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t) q(\mathbf{h}_2, \mathbf{r}_2, \boldsymbol{\lambda})| \left\{ t^{s_1} \boldsymbol{\lambda}^{s_2} \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}(\mathbf{a}, \mathbf{c}) \right|^q + m_2 t^{s_1} (1 - \boldsymbol{\lambda}^{s_2}) \left| \frac{\partial^2 \mathbf{f}}{\partial \mathbf{t} \partial \boldsymbol{\lambda}}\left(\mathbf{a}, \frac{\mathbf{d}}{m_2}\right) \right|^q \right\} dt d\boldsymbol{\lambda} \end{aligned}$$

$$\begin{aligned}
& + m_1(1-t^{s_1})\lambda^{s_2} \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{\mathbf{b}}{m_1}, \mathbf{c} \right) \right|^q + m_1 m_2 (1-t^{s_1})(1-\lambda^{s_2}) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{\mathbf{b}}{m_1}, \frac{\mathbf{d}}{m_2} \right) \right|^q \Bigg\} dt d\lambda \\
= & \left(\int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t)| t^{s_1} dt \right) \left\{ \left(\int_0^1 |q(\mathbf{h}_2, \mathbf{r}_2, \lambda)| \lambda^{s_2} d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} (\mathbf{a}, \mathbf{c}) \right|^q \right. \\
& \left. + m_2 \left(\int_0^1 |q(\mathbf{h}_2, \mathbf{r}_2, \lambda)| (1-\lambda^{s_2}) d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\mathbf{a}, \frac{\mathbf{d}}{m_2} \right) \right|^q \right\} \\
& + \left(\int_0^1 |p(\mathbf{h}_1, \mathbf{r}_1, t)| (1-t^{s_1}) dt \right) \left\{ m_1 \left(\int_0^1 |q(\mathbf{h}_2, \mathbf{r}_2, \lambda)| \lambda^{s_2} d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{\mathbf{b}}{m_1}, \mathbf{c} \right) \right|^q \right. \\
& \left. + m_1 m_2 \left(\int_0^1 |q(\mathbf{h}_2, \mathbf{r}_2, \lambda)| (1-\lambda^{s_2}) d\lambda \right) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{\mathbf{b}}{m_1}, \frac{\mathbf{d}}{m_2} \right) \right|^q \right\} \\
= & \mu(\mathbf{h}_1, \mathbf{r}_1, s_1) \left\{ \mu(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda} (\mathbf{a}, \mathbf{c}) \right|^q + m_2 \nu(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\mathbf{a}, \frac{\mathbf{d}}{m_2} \right) \right|^q \right\} \\
& + \nu(\mathbf{h}_1, \mathbf{r}_1, s_1) \left\{ m_1 \mu(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{\mathbf{b}}{m_1}, \mathbf{c} \right) \right|^q + m_1 m_2 \nu(\mathbf{h}_2, \mathbf{r}_2, s_2) \left| \frac{\partial^2 f}{\partial t \partial \lambda} \left(\frac{\mathbf{b}}{m_1}, \frac{\mathbf{d}}{m_2} \right) \right|^q \right\}.
\end{aligned}$$

Combining the above equations and inequalities reveals the assertion (3.5). The proof is completed.

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