

Fig.1. Computer system and intercommunication with another system

|  |  |  |  |
| --- | --- | --- | --- |
| Tasks | Computer system\_x | Computer system\_y | Computer system\_z |
| T1=Task1 | 0.1µs | 0.15µ | 0.12µs |
| T2=Task 2 | 0.3µs | 0.25µ | 0.32µs |
| T3=Task3 | 0.4µs | 0.45µ | 0.42µs |
| T4=Task4 | 0.2µs | 0.15µ | 0.12µs |
| T5=Task5 | 0.1µs | 0.15µ | 0.2µs |
| ... | ... | ... | ... |

Table 1. Computers systems, tasks and durations.

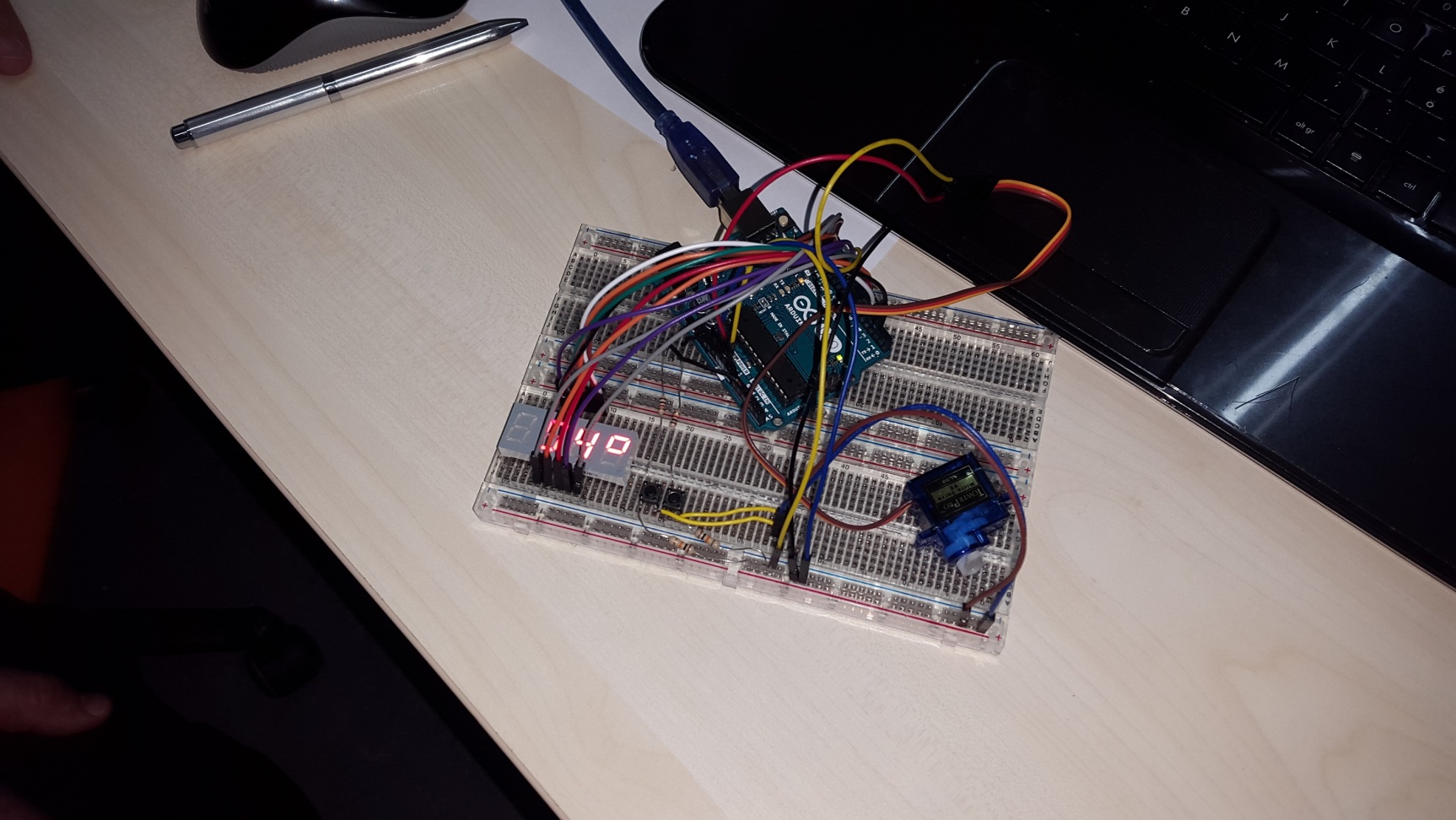
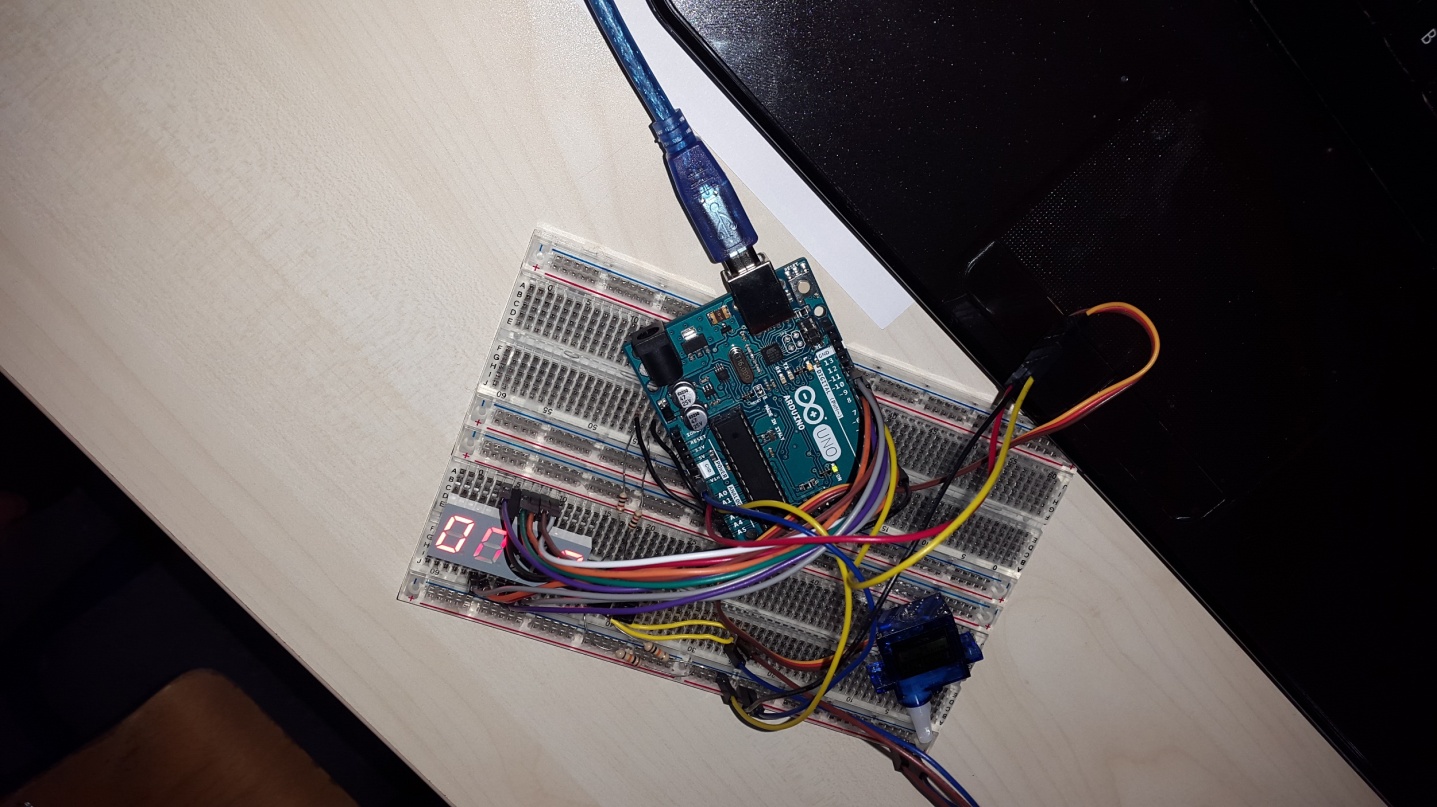
 

Fig. 2. The position and angle, Generation the current position through servomotor.



Fig. 3. Computer systems and Arduino interface