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Research paper



Nonlinear Vibration of Microbeams Based on The Elastics Foundation Using High-Order Energy Balance Method And Global Error Minimization Method

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Abstract

In this paper, nonlinear vibration of microbeams based on the nonlinear elastic foundation is investigated. The equation of motion of microbeams based on three-layered nonlinear elastic medium (shear, linear and nonlinear layers) is described by the partial differential equation by using the modified couple stress theory. The equation of motion of microbeams is transformed into the ordinary differential equation by using Galerkin method. The high-order Energy Balance method and the high-order Global Error Minimization method are used to get the frequency – amplitude relationships for the nonlinear vibration of microbeams with pinned-pinned and clamped-clamped end conditions. Comparisons between the present solutions and the privious solutions show the accuracy of the obtained results.

Keywords: Microbeams, nonlinear vibration, Energy Balance method, Global Error Minimization method.

1. Introduction

Micro- and nano-beams have been widely used in nano- and micro-sized systems and devices such as biosensors, nanowires, atomic force microscope, microactuators, nano-probes, microelectromechanical, ultra thin films and nano-electromechanical systems. In these applications, the size effect has a major role on static and dynamic deformation behavior of material and cannot be negligible [1, 2]. The classical continuum mechanics is not able to take into account the size effect in modeling of the material behavior at the nanoscale. Thus, several higher order continuum theories, such as the couple stress theory [3, 4, 5] that contains four material constants (two classical and two additional), strain gradient theory [6], micropolar theory [7], nonlocal elasticity theory [8], surface elasticity [9], have been developed to account for the size effect in the small scale structures. The classical couple stress theory is one of the other higher order continuum theories which contain two additional material length scale parameters besides the classical constants for an isotropic elastic material, elaborated by Mindlin and Tiersten [4], Toupin [3]. A modified couple stress theory was proposed by Yang et al. [10] which contain only one additional material length scale parameter in addition to the classical material constants. Also, the couple stress tensor is symmetric in this theory, this modified couple stress theory includes the secondorder displacement gradients. This modified couple stress theory is more useful than classical one due to these features.

To date, static, buckling and vibration characteristics of microbeams using the modified couple stress theory have been theoretically investigated in the context of size-dependent beam theories by the several researchers [11, 12, 13, 14, 15, 16, 17].

Recently, nonlinear static and free vibration analysis of microbeams based on the nonlinear elastic foundation using modified couple stress theory are studied by Simsek [18]. In this work, the approximate analytical expressions of nonlinear frequency of microbeams based on the nonlinear foundation are obtained and presented for the first time for pinned–pinned (P-P) and clamped– clamped (C-C) end conditions by means of He's Variational Approach (VA). Static analysis is also performed for uniformly distributed load.

Due to the limitation of the exact solution of nonlinear oscillation problems, new asymptotic methods have been increasingly developed in order to solve nonlinear differential equations such as Energy Balance method (EBM) [19], Variational Approach (VA) [20], Hamiltonian Approach (HA) [21], Global Error Minimization method (GEM) [22]. To improve the approximate solution of nonlinear oscillators, the high-order approximate methods are introducted such as the high-order Energy Balance method [23], the high-order Global Error Minimization method [22].

In this paper, the high-order Energy Balance method and the highorder Global Error Minimization method will be appied to analyse nonlinear free vibration of microbeams based on nonlinear elastic foundation. The obtained solutions are compared with the ones achived by Simsek using He's Variational Approach. Comparisons show the accuracy of the present solutions.



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2. Modelling and formulation



Fig. 1: An isotropic microbeam based on a three-layered nonlinear elastic foundation.

An isotropic microbeam of a constant thickness of h with crosssectional dimensions L and b is considered and shown in **Fig. 1**. The microbeam is based on a nonlinear elastic foundation with the spring constants k_L , k_P and k_{NL} of the Winkler elastic medium, Pasternak elastic medium and nonlinear elastic medium, respectively.

Using the modified couple theory, the equations of motion in terms of the displacements can be achieved as follows [18]:

$$\left(EI + \mu AL^{2}\right)\frac{\partial^{4}w}{\partial x^{4}} - \left[\frac{EA}{2L}\int_{0}^{L}\left(\frac{\partial w}{\partial x}\right)^{2}dx\right]\frac{\partial^{2}w}{\partial x^{2}} + k_{L}w - k_{P}\frac{\partial^{2}w}{\partial x^{2}} + k_{NL}w^{3} + \rho A\frac{\partial^{2}w}{\partial t^{2}} = q(x,t)$$
(1)

where *N* is the axial normal force, *E* is the elasticity modulus, *A* is the area of the cross-section, *I* is the inertia moment of the cross-section, $\mu = E/2(1+v)$ is known as shear modulus where *v* is the Poisson's ratio, ρ is density, *q* is the distributed transverse load. The following dimensionless parameters are introduced:

$$\overline{x} = \frac{x}{L}, \ \overline{w} = \frac{w}{r}, \ t = \overline{t} \sqrt{\frac{\rho A L^4}{EI}}, \ \eta = \frac{l}{h}, \ S = 1 + \frac{6\eta^2}{1 + \nu},$$

$$K_L = \frac{k_L L^4}{EI}, \ K_P = \frac{k_P L^2}{EI}, \ K_{NL} = \frac{k_{NL} r^2 L^4}{EI}, \ \overline{q} = \frac{q L^4}{EIr}.$$
(2)

where $r = \sqrt{I/A}$ is the radius of gyration of the cross-section, and it is noted that *l* denotes the material length scale parameter which is an additional material parameter enabling the theory to capture the size-dependency. Considering Eq. (2), Eq. (1) can be written in the non-dimensional form as:

$$S\frac{\partial^{4}\overline{w}}{\partial\overline{x}^{4}} - \left[\frac{1}{2}\int_{0}^{1} \left(\frac{\partial\overline{w}}{\partial\overline{x}}\right)^{2} d\overline{x}\right]\frac{\partial^{2}\overline{w}}{\partial\overline{x}^{2}} + K_{L}\overline{w} - K_{P}\frac{\partial^{2}\overline{w}}{\partial\overline{x}^{2}} + K_{NL}\overline{w}^{3} + \frac{\partial^{2}\overline{w}}{\partial\overline{t}^{2}} = \overline{q}$$
(3)

In order to apply the Galerkin method, displacement function $\overline{w}(\overline{x}, \overline{t})$ can be expanded into a finite series as follows:

$$\overline{w}(\overline{x},\overline{t}) = Q(\overline{t})\phi(\overline{x}) \tag{4}$$

where $Q(\bar{t})$ is the unknown time-dependent coefficient to be determined and $\phi(\bar{x})$ is the basis (test) function which must satisfy the kinematic boundary conditions. The following test functions can be chosen for PP and CC boundary conditions: for Pinned – Pinned (P-P) microbeam:

$$\phi(\overline{x}) = \sin(\pi \overline{x}) \tag{5}$$

for Clamped - Clamped microbeam:

where $\phi(\bar{x})$ is normalized in such a way that $\phi(0.5) = 1$. Substituting the approximate solution in Eq.(4) into Eq.(3), then multiplying both sides of the resulting equation with $\phi(\bar{x})$ and integrating it over the domain (0, 1) yields:

$$\ddot{Q}(\bar{t}) + (D_1 + D_2 + K_L)Q(\bar{t}) + (D_3 + D_4)Q^3(\bar{t}) = F(\bar{t})$$
(7)

Here the coefficients D_1 , D_2 , D_3 , D_4 and F in Eq. (7) can be expressed as:

$$D_{1} = \frac{\int_{0}^{1} S\phi^{(4)}\phi d\overline{x}}{\int_{0}^{1} (\phi)^{2} d\overline{x}}, D_{2} = -\frac{\int_{0}^{1} K_{p} \phi^{*}\phi d\overline{x}}{\int_{0}^{1} (\phi)^{2} d\overline{x}}, D_{3} = -\frac{\frac{1}{2} \int_{0}^{1} (\phi^{*})^{2} d\overline{x}}{\int_{0}^{1} (\phi)^{2} d\overline{x}}, D_{4} = \frac{\int_{0}^{1} K_{NL}(\phi)^{4} d\overline{x}}{\int_{0}^{1} (\phi)^{2} d\overline{x}}, F = \frac{\int_{0}^{1} \overline{q} \phi d\overline{x}}{\int_{0}^{1} (\phi)^{2} d\overline{x}}$$
(8)

where $\phi^{(4)}$ is the fourth derivative of ϕ with respect to the axial coordinate \overline{x} , and the prime notations also denote the differentiations with respect to the axial coordinate.

3. Analyzing of nonlinear free vibration

The microbeam is subjected to the following initial conditions:

$$Q(0) = \alpha, \ \dot{Q}(0) = 0$$
 (9)

where $\alpha = w_{\text{max}}(0.5)/r$ is the dimensionless maximum vibration amplitude of the microbeam.

By omitting the forcing term F for free vibration analysis, Eq. (7) can be rewritten in a compact form as follows:

$$\ddot{Q}(\overline{t}) + g_1 Q(\overline{t}) + g_2 Q^3(\overline{t}) = 0$$
⁽¹⁰⁾

where $g_1 = D_1 + D_2 + K_L$ and $g_2 = D_3 + D_4$.

In the next section, the high-order Energy Balance method and the high-order Global Error Minimization method will be applied to find approximate solutions of Eq. (10) with the initial conditions (9).

3.1. Application of the high-order Energy Balance method

3.1.1. The first-order approximate

The basic of the energy balance method (EBM) was proposed by He [19]. The variational of Eq. (10) is given as follows:

$$J(Q) = \int_{0}^{T/4} \left(-\frac{\dot{Q}^2}{2} + g_1 \frac{Q^2}{2} + g_2 \frac{Q^4}{4} \right) d\bar{t}$$
(11)

Here $T=2\pi/\omega$ is the period of the nonlinear oscillator. For the first-order approximation, the following approximate solu-

tion of Eq. (10) can be assumed:

$$Q_1(\bar{t}) = \alpha \cos(\omega \bar{t}) \tag{12}$$

where α and ω are the initial amplitude and natural frequency of the nonlinear oscillator, respectively.

With the approximate solution (12), the Hamiltonian of Eq. (10) is given as follows:

$$H_{1} = \frac{1}{2}\alpha^{2}\omega^{2}\sin^{2}(\omega \bar{t}) + \frac{1}{2}g_{1}\alpha^{2}\cos^{2}(\omega \bar{t}) + \cos^{4}(\omega \bar{t}) =$$

$$= \frac{1}{2}g_{1}\alpha^{2} + \frac{1}{4}g_{2}\alpha^{4}$$
(13)

Eq. (13) yields the following residual equation:

$$R_{1}(\bar{t}) = \frac{1}{2}\alpha^{2}\omega^{2}\sin^{2}(\omega\bar{t}) + \frac{1}{2}g_{1}\alpha^{2}\cos^{2}(\omega\bar{t}) + \cos^{4}(\omega\bar{t}) - \frac{1}{2}g_{1}\alpha^{2} - \frac{1}{4}g_{2}\alpha^{4}.$$
(14)

If, by chance, the exact solution of Eq. (10) had been chosen as the trial function, then it would be possible to make R_1 zero for all values of \bar{t} by appropriate choice of ω . Since Eq. (12) is only an approximation to the exact solution, R_1 can not be made zero everywhere. Collocation at $\omega \bar{t} = \pi/4$, from Eq. (14) we obtain the first-order approximate frequency:

$$\omega_{EBM1} = \sqrt{g_1 + \frac{3}{4}g_2\alpha^2}$$
(15)

3.1.2. The high-order approximate

In order to improve the accuracy of the Energy Balance method, let us define $Q(\bar{t})$ as follows:

$$Q_2(\overline{t}) = \alpha_1 \cos(\omega \overline{t}) + \alpha_2 \cos(3\omega \overline{t})$$
(16)

Eq. (16) must satisfy the initial conditions (9); therefore, we have:

$$\alpha_1 + \alpha_2 = \alpha \tag{17}$$

Thus, the approximate solution (16) can be rewritten:

$$Q_{2}(\overline{t}) = \alpha_{1} \cos(\omega \overline{t}) + (\alpha - \alpha_{1}) \cos(3\omega \overline{t})$$
(18)

With the approximate solution (18), we have the following residual equation:

$$R_{2}(\overline{t}) = \frac{1}{2} \left[-\alpha_{1}\omega\sin(\omega\overline{t}) - 3(\alpha - \alpha_{1})\omega\sin(3\omega\overline{t}) \right]^{2} + \frac{1}{2} g_{1} \left[\alpha_{1}\cos(\omega\overline{t}) + 3(\alpha - \alpha_{1})\cos(3\omega\overline{t}) \right]^{2} + \frac{1}{4} g_{2} \left[\alpha_{1}\cos(\omega\overline{t}) + 3(\alpha - \alpha_{1})\cos(3\omega\overline{t}) \right]^{4} - \frac{1}{2} g_{1}\alpha^{2} - \frac{1}{4} g_{2}\alpha^{4}$$

$$(19)$$

It requires an system of two equations to find two unknown parameters A_1 and ω . Using Galerkin method as a weighting function, with $\cos(\omega t)$ and $\cos(3\omega t)$ are used as weighting functions, the following systems can be obtained [23]:

$$\int_{0}^{T/4} R_2(\overline{t}) \cos(\omega \overline{t}) d\overline{t} = 0$$
 (20)

$$\int_{0}^{T/4} R_2(\bar{t}) \cos(3\omega \bar{t}) d\bar{t} = 0$$
(21)

By inserting Eq. (19) into Eqs. (20) and (21), after some mathematical amendments, we have:

$$-\frac{75776}{4095}g_{2}\alpha_{1} + \frac{16}{35}g_{1}\alpha_{1}^{2} - \frac{10240}{3003}g_{2}\alpha_{1}^{3} + \frac{512}{1287}g_{2}\alpha_{1}^{4}$$

$$-\frac{32}{21}g_{1}\alpha_{1} - \frac{528}{35}\alpha_{1}\omega^{2} + \frac{184}{105}\alpha_{1}^{2}\omega^{2} + \frac{1224}{35}\omega^{2} \qquad (22)$$

$$+\frac{62464}{5005}g_{2}\alpha_{1}^{2} - \frac{136}{35}g_{1} - \frac{195904}{5005}g_{2} = 0.$$

$$\frac{1632256}{45045}g_{2}\alpha_{1} - \frac{176}{315}g_{1}\alpha_{1}^{2} + \frac{22528}{4095}g_{2}\alpha_{1}^{3}$$

$$-\frac{3584}{6435}g_{2}\alpha_{1}^{4} + \frac{928}{315}g_{1}\alpha_{1} + \frac{176}{35}\alpha_{1}\omega^{2} \qquad (23)$$

$$-\frac{104}{105}\alpha_{1}^{2}\omega^{2} - 8\omega^{2} - \frac{44032}{2145}g_{2}\alpha_{1}^{2} + \frac{8}{9}g_{1} + \frac{448}{45}g_{2} = 0.$$

By solving Eqs. (22) and (23) simultaneously, we can obtain the second-order approximate amplitude-frequency relationship.

3.2. Application of the high-order Global Error Minimization method

A modified variational approach called Global Error Minimization (GEM) method was introduced by Yadollah Farzaneh and Ali Akbarzadeh Tootoonchi [22]. In this section, we will apply this method to find the approximate solution of Eq. (10).

3.2.1. The first-order approximate

It is similar to the Energy Balance method, with the first-order approximate, we begin the procedure with the simplest trial solution:

$$Q_1(\overline{t}) = \alpha \cos(\omega \overline{t}) \tag{24}$$

Next, we convert Eq. (10) to the minimization problem:

Minimize
$$E(\dot{Q}_1, Q_1, \bar{t}) = \int_{0}^{1} (\ddot{Q}_1 + g_1 Q_1 + g_2 Q_1^3)^2 d\bar{t}, T = \frac{2\pi}{\omega}$$
 (25)

s. t.
$$Q_1(0) = \alpha, \quad \dot{Q}_1(0) = 0$$

By replacing Eq. (24) in Eq. (25) and performing the integration we get:

$$Minimize \ E(\dot{Q}_1, Q_1, \bar{t}) = \frac{\alpha^2 \pi \begin{pmatrix} 5g_2^2 \alpha^4 - 16\omega^2 g_1 - 12\omega^2 g_2 \alpha^2 \\ +8\omega^4 + 12g_1g_2 \alpha^2 + 8g_1^2 \end{pmatrix}}{8\omega}$$
(26)

Thus, from the condition

$$\frac{\partial E\left(\dot{Q}_{1},Q_{1},\overline{t}\right)}{\partial \omega}=0$$

we get the first-order approximate frequency of the oscillator:

$$\omega_{GEM1} = \frac{1}{6}\sqrt{9g_2\alpha^2 + 12g_1 + 3\sqrt{39g_2^2\alpha^4 + 96g_1g_2\alpha^2 + 64g_1^2}}$$
(27)

3.2.2. The high-order approximate

Now, to improve our analytical approximation, we will add additional terms to the trial solution by considering the second-order approximation:

$$Q_2(\overline{t}) = \alpha_1 \cos(\omega \overline{t}) + (\alpha - \alpha_1) \cos(3\omega \overline{t})$$
(28)

With the new trial solution in Eq. (28), Eq. (10) is converted to a minimization problem:

Minimize
$$E(\dot{Q}_2, Q_2, \bar{t}) = \int_0^t (\ddot{Q}_2 + g_1 Q_2 + g_2 Q_2^3)^2 d\bar{t}, T = \frac{2\pi}{\omega}$$

s. t. $Q_2(0) = \alpha, \ \dot{Q}_2(0) = 0$
(29)

The solution of Eq. (29) could be found by using the conditions:

$$\frac{\partial E(\dot{Q}_2, Q_2, \bar{t})}{\partial \omega} = \frac{\partial E(\dot{Q}_2, Q_2, \bar{t})}{\partial \alpha_1} = 0$$
(30)

. .

Substituting Eq. (28) into Eq. (29), and from the conditions (30), after some mathematical operations, we get:

$$31488\alpha_{1}^{2}\omega^{4} - 622080\omega^{4}\alpha_{1} - 256g_{1}^{2}\alpha_{1}^{2} + 2560g_{1}^{2}\alpha_{1} \\ -880g_{2}^{2}\alpha_{1}^{6} + 400000g_{2}^{2}\alpha_{1}^{3} + 31200g_{2}^{2}\alpha_{1}^{5} \\ -480000g_{2}^{2}\alpha_{1}^{4} + 4800000g_{2}^{2}\alpha_{1} - 19200000g_{2}^{2}\alpha_{1}^{2} \\ -2560\alpha_{1}^{2}\omega^{2}g_{1} - 4992\alpha_{1}^{4}\omega^{2}g_{2} + 138240\alpha_{1}^{3}\omega^{2}g_{2} \\ -1420800\alpha_{1}^{2}\omega^{2}g_{2} + 46080\alpha_{1}\omega^{2}g_{1} + 6912000\alpha_{1}\omega^{2}g_{2} \\ +768000g_{1}g_{2}\alpha_{1} + 3110400\omega^{4} - 230400\omega^{2}g_{1} \\ -17280000\omega^{2}g_{2} - 12800g_{1}^{2} - 1920000g_{1}g_{2} \\ -80000000g_{2}^{2} = 0. \\ 20992\omega^{4}\alpha_{1} - 207360\omega^{4} + 512g_{1}^{2}\alpha_{1} - 2560g_{1}^{2} \\ +5280g_{2}^{2}\alpha_{1}^{5} - 12000000g_{2}^{2}\alpha_{1}^{2} - 156000g_{2}^{2}\alpha_{1} \\ +1920000g_{2}^{2}\alpha_{1}^{3} - 4800000g_{2}^{2} + 38400000g_{2}^{2}\alpha_{1} \\ -5120\omega^{2}\alpha_{1}g_{1} - 19968\alpha_{1}^{3}\omega^{2}g_{2} + 414720\alpha_{1}^{2}\omega^{2}g_{2} \\ -2841600\alpha_{1}\omega^{2}g_{2} + 46080\omega^{2}g_{1} + 6912000\omega^{2}g_{2} \\ +3584g_{1}\alpha_{1}^{3}g_{2} - 61440g_{1}\alpha_{1}^{2}g_{2} + 384000g_{1}\alpha_{1}g_{2} \\ -768000g_{1}g_{2} = 0. \\ \end{cases}$$
(31)

Eqs. (31) and (32) contain two unknown parameters ω and α_1 . By solving Eqs. (31) and (32) simultaneously, we can obtain the second-order approximate amplitude-frequency relationship of the oscillator.

Higher-order approximate solutions of the EBM and GEM can be established by the similar manner. However, with higher-order approximations, it is required to solve a complex set of algebraic equations to achieve the frequency of the oscillator.

4. Numerical results

The nonlinear frequencies of P-P and C-C Microbeams obtained in this work are compared with the ones achived by Simsek [18]. In this work, using He's Variational Approach (VA), Simsek obtained the nonlinear frequencies as follows:

$$\omega_{VA} = \sqrt{g_1 + \frac{3}{4}g_2\alpha^2}$$
(33)

It can be seen that the appriximate frequency ω_{VA} in Eq. (33) is the same as the approximate frequency obtained by the firt-order Energy Balance method in Eq. (15). Tables 1 and 2 show comparions the approximate frequencies with the exact frequencies for P-P and C-C Microbeams, respectivelly. Note that these comparisons are calculated with $K_L=0$, $K_P=0$, $K_{NL}=0$ and length scale parameter l=0. The exact frequency of the oscillator can be seen Appendix. From these Tables, the accuaracy of the present solutions can be observed.

Table 1: Comparion of the approximate frequencies for P-P Microbeam

α	ω_{ex}	ω_{VA} (error %)	ω_{GEM1} (error %)	\mathcal{O}_{GEM2} (error %)	ω_{EBM1} (error %)	$\omega_{_{EBM2}}(\text{error \%})$
0.01	9.86969	9.86969 (<mark>0</mark>)	9.86969 (<mark>0</mark>)	9.86969 (<mark>0</mark>)	9.86969 (<mark>0</mark>)	9.86969 (<mark>0</mark>)
0.1	9.87885	9.87885 (0)	9.87885 (0)	9.87885 (0)	9.87885 (0)	9.87885 (0)
1	10.74956	10.75515 (0.05200)	10.75887 (0.08661)	10.74964 (0.00074)	10.75515 (0.05200)	10.74791 (0.01535)
2	13.00593	13.05626 (0.38698)	13.08939 (0.64171)	13.00839 (0.01891)	13.05626 (0.38698)	12.99184 (0.10834)
3	16.04479	16.17983 (0.84164)	16.26748 (1.38793)	16.05582 (0.06875)	16.17983 (0.84164)	16.00796 (0.22954)
4	19.50249	19.73921 (1.21379)	19.89107 (1.99246)	19.52739 (0.12768)	19.73921 (1.21379)	19.43864 (0.32739)

Table 2: Comparison of the approximate frequencies for C-C Microbean

α	ω_{ex}	ω_{VA} (error %)	ω_{GEM1} (error %)	ω_{GEM2} (error %)	ω_{EBM1} (error %)	ω_{EBM2} (error %)
0.01	22.79293	22.79293 (0)	22.79293 (0)	22.79293 (0)	22.79293 (0)	22.79293 (0)
0.1	22.79822	22.79822 (0)	22.79822 (0)	22.79822 (0)	22.79822 (0)	22.79822 (0)
1	23.31999	23.32097 (0.00420)	23.32161 (0.00695)	23.31999 (0)	23.32097 (0.00420)	23.31969 (0.00129)
2	24.82505	24.83796 (0.05200)	24.84655 (0.08661)	24.82524 (0.00077)	24.83796 (0.05200)	24.82124 (0.01535)
3	27.128750	27.17877 (0.18438)	27.21192 (0.30658)	27.13030 (0.00571)	27.17877 (0.18438)	27.11442 (0.05282)
4	30.035910	30.15214 (0.38697)	30.22867 (0.64177)	30.04161 (0.01898)	30.15214 (0.38697)	30.00337 (0.10834)

The nonlinear frequency ratios of P-P and C-C Macrobeams are compared with those of Azraret et al. [24] for various values of the dimensionless maximum vibration amplitude ($\alpha = 1, 2, 3, 4$), which are presented in Tables 3 and 4, respectively. Again, the accuracy of the present frequencies can be seen.

It can be seen from Tables 3 and 4 that the frequency ratio increases as the initial amplitude α increases, when α is small the linear frequency and the nonlinear frequency of the oscillatior are approximately equal.

Table 3: Comparion of the approximate frequency ratios for P-P Macrobeam

α	Azrar et al.	VA (error %)	GEM 1 (error %)	GEM 2 (error %)	EBM 1 (error %)	EBM 2 (error %)
1	1.0891	1.0897 (0.0573)	1.0901 (<mark>0.0919</mark>)	1.0891 (<mark>0.0060</mark>)	1.0897 (0.0573)	1.0889 (<mark>0.0100</mark>)
2	1.3177	1.3228 (0.3927)	1.3262 (0.6475)	1.3180 (0.0246)	1.3228 (0.3927)	1.3163 (0.1025)
3	1.6256	1.6393 (<mark>0.8464</mark>)	1.6482 (1.3927)	1.6267 (0.0734)	1.6393 (<mark>0.8464</mark>)	1.6219 (<mark>0.2248</mark>)
4		2.0000 ()	2.0153 ()	1.9785 ()	2.0000 ()	1.9695 ()

Time history and phase trajectory of responses for P-P and C-C microbeams, with $\alpha = 1$, l/h = 0.25, $K_P = 10$, $K_L = 40$ and $K_{NL} = 50$, using various differential methods are presented in **Figs. 2** and **3**,

respectively. High agreement between the approximate solutions can be observed.



 Table 4: Comparion of the approximate frequency ratio for C-C Macrobeam

Fig. 3: Time history and phase trajectory of response for C-C microbeam

The effects of the initial amplitude α on the nonlinear frequency ratio (ω_{NL}/ω_L) and the nonlinear frequency ω_{NL} of microbeams based on the dimensionless material length scale

Dimensionless time

parameter (l/h) are plotted in **Figs. 4** and **5**. When the dimensionless material length scale parameter increases, then the frequency ratio decreases but the nonlinear frequency increases.

Dimensionless deflection



Fig. 4: The effect of the initial amplitude on the frequency ratio of microbeams based on the dimensionless material length scale parameter with $K_P=100$, $K_L=100$ and $K_{NL}=100$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)



Fig. 5: The effect of the initial amplitude on the nonlinear frequency of microbeams based on the dimensionless material length scale parameter with K_{P} =100, K_{L} =100 and K_{NL} =100; (a) P-P microbeam, (b) C-C microbeam; (* : VA and EBM1, - : GEM1)

The variations of the nonlinear frequency ratio and the nonlinear frequency with the initial amplitude for various values of the dimensionless length scale parameter are investigated and showed in **Figs. 6** and **7**. We see that the frequency ratio and the nonlinear frequency of microbeams increase when the dimensionless amplitude increases.



Fig. 6: The variation of the frequency ratio of microbeams with the dimensionless amplitude for various values of the dimensionless material length scale parameter with $K_P=10$, $K_L=100$ and $K_{NL}=10$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)



Fig. 7: The variation of the nonlinear frequency of microbeams with the dimensionless amplitude for various values of the dimensionless material length scale parameter with $K_P=10$, $K_L=100$ and $K_{NL}=10$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)

Comparisons of the effect of the coefficients of the nonlinear foundation on the vibration behavior of the microbeams using various methods are also investigated. First, the variations of the nonlinear frequency ratio and the nonlinear frequency with the Winkler parameter for various values of the dimensionless length scale parameter are showed in **Figs. 8** and **9**. We see that when the dimensionless amplitude increases, then the frequency ratio of microbeams decreases but the nonlinear frequency of microbeams increases.



Fig. 8: The variation of the frequency ratio of microbeams with the Winkler parameter for various values of the dimensionless material length scale parameter with $K_P=10$, $K_{NL}=100$ and $\alpha=1$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)



Fig. 9: The variation of the nonlinear frequency of microbeams with the Winkler parameter for various values of the dimensionless material length scale parameter with $K_P=10$, $K_{NL}=100$ and $\alpha=1$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)

Second, the variations of the nonlinear frequency ratio and the nonlinear frequency with the Pasternak parameter for various values of the dimensionless length scale parameter are presented in **Figs. 10** and **11**. As the same as the effect of the Winkler parameter

ter on the vibration behavior of the microbeams, when the dimensionless amplitude increases, then the frequency ratio of microbeams decreases but the nonlinear frequency of microbeams increases.



Fig. 10: The variation of the frequency ratio of microbeams with the Paternak parameter for various values of the dimensionless material length scale parameter with $K_L = 100$, $K_{NL} = 100$ and $\alpha = 1$; (a) P-P microbeam, (b) C-C microbeam; (* : VA and EBM1, - : GEM1)



Fig. 11: The variation of the nonlinear frequency of microbeams with the Paternak parameter for various values of the dimensionless material length scale parameter with $K_L=100$, $K_{NL}=100$ and $\alpha=1$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)

And last, the variations of the nonlinear frequency ratio and the nonlinear frequency with the nonlinear foundation parameter for various values of the dimensionless length scale parameter are investigated and presented in **Figs. 12** and **13**. It is not the same as the effect of the Winkler parameter and the Pasternak parameter on the vibration behavior of the microbeams, when the dimensionless amplitude increases, then all of the frequency ratio of microbeams and the nonlinear frequency of microbeams increase.



Fig. 12: The variation of the frequency ratio of microbeams with nonlinear foundation parameter for various values of the dimensionless material length scale parameter with $K_P=100$, $K_L=100$ and $\alpha=1$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)



Fig. 13: The variation of the nonlinear frequency of microbeams with nonlinear foundation parameter for various values of the dimensionless material length scale parameter with $K_P=100$, $K_L=100$ and $\alpha=1$; (a) P-P microbeam, (b) C-C microbeam; (*: VA and EBM1, -: GEM1)

5. Conclusion

In this work, nonlinear free vibration of microbeams based on nonliear elastic foundation with three layers is intestigated using the high-order Energy Balance method and the high-order Global Error Minimization method. The accuracy of approximate solutions has been improved by using the second-order approximation. The frequency-amplitude relationships of microbeams with P-P and C-C end conditions are obtained in closed-forms. The present solutions are compared with the previous published ones. Comparisons show the accuracy of the obtained solutions. The effects of the initial amplitude, the dimensionless material length scale parameter and the coefficients of the nonlinear foundation on the vibration behavior of the microbeams are investigated.

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Appendix

For the osccillator given in the form:

$$\ddot{X} + a_1 X + a_2 X^3 = 0, X(0) = A, \dot{X}(0) = 0$$

The exact frequency is:

$$\omega_{ex} = \frac{2\pi}{4\sqrt{2} \int_{0}^{\pi/2} \frac{dt}{\sqrt{a_2 A^2 \cos^2(t) + a_2 A^2 + 2a_1}}}$$

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