

Result of Review

**International Journal of Engineering
and Technology(UAE)**



Science Publishing
Corporation

Title: Design Fuzzy Neural Petri Net Controller for Trajectory Tracking Control of Mobile Robot

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Decision of Paper Selection

- Accept submission, no revisions required
- Accept submission, revisions required**
- Revise and resubmit for review
- Decline submission

What should you do?

- Revise the paper according to the comments and resubmit it by email.
- Write a detailed email on replying the review report explain how you edited your paper to meet the reviewer comments.

Review Comments

Evaluation	Grade 5=Excellent 4=Good 3=Average 2=Below Average 1=Poor
Overall evaluation on the paper	3
Originality of the paper	4
Significance	3
Contribution to existing knowledge	3
Clarity of presentation	2
Adequacy of literature review	3
Soundness of methodology	3
Evidence supports conclusion	3

Comments and Suggestions

It is an interesting paper, well written but it needs some modifications to be ready for publication.

- The English must be carefully checked.
- Similarity index (checked by iThenticate) is high, please revise to make it a little lower and single source matches are not > 5%.
- More references should be found and they should cover the last 5 years.
- Lastly, the references should be made according to the journal format.

I recommend accepting the paper after the modifications suggested have been incorporated.

Please make substantial changes in the revised version and resubmit it again, provide authors' respond to the comments.