

# Estimation of Optimum Rendezvous Point for Mobile Sink (ORP-MS) in WSN

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## Abstract

Clustering of the sensors in wireless sensor network is done to achieve energy efficiency. The nodes, which are unable to join any cluster, are referred to as isolated nodes and tend to transfer information straight to the base station. It is palpable that isolated nodes and cluster heads communicate with the base station and tend to exhaust their energy leaving behind coverage holes. In this paper, we propose the innovative clustering scheme using mobile sink approach to extend networks lifetime. The proposed (ORP-MS) algorithm is implemented in MATLAB 2017a and the results revealed that the proposed algorithm outdid the existing algorithms in terms networks lifetime and energy efficiency simultaneously achieved high throughput.

**Keywords**—WSN; Clustering protocol; Mobile Sink; Tour Plan; Energy efficiency; Network lifetime.

## 1. Introduction

Wireless Sensor Networks (WSN) are jam-packed with ambiguity and inaccuracies are prevalent to it. Previous years have seen lot of research in field of WSN. Though, challenges and probabilistic processes are innate to WSN, yet it finds vast application in industrial as well as military applications [1]–[3]. WSN integrate vast measure of elfin sensor nodes which consist of a radio interface, processor, A to D converter, sensors, memory, and a battery. Nodes are required to sense, collect, save and propel data to sink whenever required using radio communication [4]. In Random, deployment nodes are usually scattered (Fig-1). The density of nodes can be controlled but up to some extent [5]. This technique is best suited for the bids where Region of observation (ROI) is unapproachable e.g. war zones. Clustering is done to achieve energy efficiency in arbitrarily deployed sensor network [6]. In Clustering scheme group of nodes form a cluster and elect one node as Cluster Head (CH), which is responsible to communicate with the base station (BS). Information sensed by the sensors is sent to CH, which temporarily stores it.

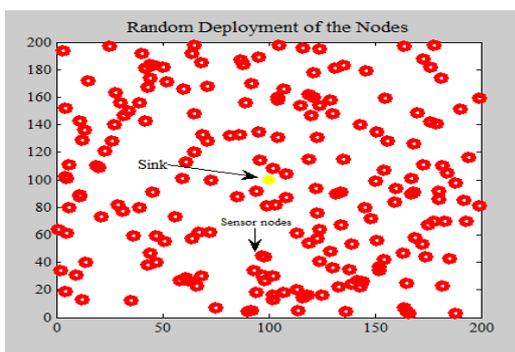


Fig. 1: Random Deployment

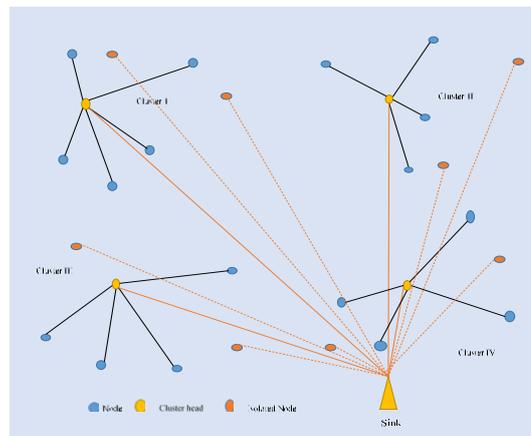


Fig. 2: Clustered WSN with Remote Sink

Finally the information gathered by nodes is communicated to BS, after fixed duration of time [3], [7]–[11]. In clustering the nodes which are unable to join the cluster are called as isolated nodes and are responsible for communicating information directly to the Base station (BS) [12]. Now as is apparent that either Cluster Head (CH) or the isolated node communicates with the BS, so, CH and isolated node tend to drain their energy soon in comparison with other sensors deployed in same network. The dead nodes give rise to coverage holes known as coronas in the network [13]. In the stationary sink setup of WSN the nodes which are situated nearer to the sink are extra prone to drain their energy before other nodes in the network, due to concentration of gen towards sink. The movement of gen in various application follow many to one protocol where the nodes near to the sink heavy traffic as compared to other nodes. Therefore, sensors near to the sink diminish their energy sooner, causing formation of coronas. This snag is addressed effectively in [12], [14]. These dead nodes cause ailment in the network and reduces the sensing reportage of the network.

Additionally, with more dead nodes around the sink, the sink might become unreachable and data collected by nodes may not be retrieved.

Subsequently, algorithms for stationary base station to conform load matching has to mitigate uniform energy consumption in the system. This is why the mobile sink came to picture [15]–[17].

In this study, we propose an innovative algorithm, using the model of mobile sink, which plummets the energy consumption of CH and isolated nodes during communication with sink. Entire geographic area to be observed by the network is divided in virtual zones. The localization [18] algorithm is implemented so that each node becomes aware of its coordinates. Then, clustering is implemented leading every zone to have its cluster and cluster head. Every zone sends information regarding location, cluster head ID, and cluster id to the base station. This information enables BS to identify isolated nodes in every zone.

Depending on the information gathered regarding isolated nodes, BS now identifies the location in each zone to move for data collection. The location is fixed such that the coordinates of the rendezvous point is approximately in between cluster head and isolated nodes, which tentatively is the region to develop the coronas in future and helps prolonging the appearance of coronas in the network. Hence, prolongs the network's lifetime.

This paper is further organized as follows. Section II gives the background of the work carried out until date, section III defines the system model having energy saving analysis of proposed scheme and there after results are discussed followed by concluding statement.

## 2. Related Work

Non-uniform energy diminution is a bodacious issue of the clustering protocols with immovable sink for WSNs. Cluster heads and isolated nodes invest extra energy to communicate unswervingly with the base station. This causes non-uniform energy consumption in the network resulting in uncovered regions plummeting efficiency of the network. Energy conservation is a vital snag in WSN and is dually addressed by investigators all around the globe. Energy efficient clustering schemes having stationary base station are presented in [3], [7], [11], [19]. Mobile Sink schemes are elaborated in [16], [17], [20]–[29]. Mobile sinks are gathering a lot of attention these days, lot of researchers have investigated the option of mobile sink in smart city network as well. To resolve energy conservation issue for WSN, the authors in [22] suggest a Distributed Energy-efficient Clustering Algorithm for moving-sink centered WSNs, where the sink travels about the target zone with a static route and velocity. The suggested clustering procedure, binds individual sensor node with a CH by means of single or multi-hop communiqué, where a CH conveys its information packet to the sink once distance among them is least. Consequently, the precise movement of the sink around the network aids in matching the energy depletion of the sensor networks. The investigational outcomes prove the competence of their suggested procedure over the present state-of-the-art procedures in terms of dissimilar metrics like, network lifespan, energy depletion, etc.

A Virtual Grid based Dynamic Routes Adjustment (VGDR) system for the mobile sink was presented in [24] to curtail the cost of communication. Authors divided the entire geographic region to smaller areas named grids and the nodes, which were close to center, were elected as advance nodes. Cell header nodes concept was built. The sink traversed the geographic region collecting data from header nodes. Authors in [25] suggested mixed integer programming and extended the lifetime using mobile sink. In [26] convex optimization model was built using support vector regression to suggest ideal trajectory for sink, which in turn effected the network's lifespan. The Wireless Charging Vehicle was used in [29], which was used to traverse the network area and charge the sensor nodes without any physical contact.

In [28], the authors deliberated the routing algorithm which rotates around on the optimal number of hops amid source and sink. The classical use of mixed-integer programming based on the

Lagrangian relaxation scheme, to pronounce crucial parameter, which oversee the hop-by-hop switching. Author in [27] presented a safe clustering algorithm for mobile sink scenario. The approach presented was to keep a watch on malicious node and remove it as soon as it is detected. They proposed minimum and well-balanced clusters for WSN.

The author in [30] proposed DCFly i.e. data collection fly which was well suited for random deployment in harsh terrain. Miniature aerial vehicle was proposed to collect data by flying above the deployed field. Author in [31] proposed multi sink placement in wireless sensor networks.

All the above work based on cluster and non-clustered structure with mobile sink have either not taken into account the presence of isolated nodes, while deciding the rendezvous point for the sink node or they have considered the continuous movement of the sink around the network during the data movement tour of the sink. Models with the continuous movement of the sink node would give less communication time with the cluster heads which furthermore leads to lesser throughput of the network. On the other hand, the models sans the presence of the isolated nodes would lead to more energy consumption by the isolated nodes as the distance of the sink from the isolated would be more.

## 3. System model

### A. Motivation

Agility, Detecting and interaction with the base station, are the processes, which requires energy of sensor node. After clustering algorithm is implemented, some nodes become isolated due to various reasons. If isolated node is at far off from base station, isolated node is destined to drain its energy causing incomplete coverage thereby reducing network's lifetime. If second stage of clustering is done for isolated nodes [3] and mobile sink route is planned such that the rendezvous point is selected to be a centroid of header nodes which finally transfer data to sink network's life time can be overwhelmingly augmented.

### B. Network Model

Let the entire network of area  $N \times N$  square units be alienated into  $M$  zones with area of  $K \times K$  square units. Also presume that ' $n_{i^{\text{th}}}$ ' be the number of nodes in ' $i^{\text{th}}$ ' zone of the network. Suppose ' $\rho_s$ ' is the density of nodes in zone ' $i$ ', of area  $K \times K$  square units. (For the sake of simplicity and understanding, we assume network to be divided into 4 zones)

### C. Notations

The following notations are used in this paper:

- 1)  $n = \{n_1, n_2, \dots, n_i\}$ , set of sensor nodes, where  $n_i$  is individual node.
- 2)  $CH = \{CH_1, CH_2, \dots, CH_i\}$ , set of Cluster Heads, where  $CH_i$  is individual CH.
- 3)  $Rp = \{Rp_1, Rp_2, \dots, Rp_m\}$ , Rendezvous points in each zone

### D. Elucidation

- 1) Cluster Head. The advance node elected to transmit information of sensors in cluster to the sink node.
- 2) Connected node. The nodes which are part of cluster and sends its data to sink node via CH.(con)
- 3) Isolated nodes. The nodes, which are not in communicating range of CH and sends its data directly to sink node. (uncon)
- 4) Zone. The part of network having its own Cluster Head

## E. Localization Model

In the proposed study, initially, Received Signal Strength Indicator (RSSI) based adaptive localization algorithm is used to approximate the coordinates of each node. We place 3 lantern nodes for enabling rest of the nodes to evaluate their co-ordinates. We make one more assumption that path loss exponent for the pair of nodes will remain same even if their relative positions are shifted. For sake of understanding, we take an example of node 's' in Fig-4 below. Node is at distance of  $d'_{la}$  from lantern node  $l_a$  at  $(x'_{la}, y'_{la})$ ,  $d'_{lb}$  from lantern node  $l_b$  at  $(x'_{lb}, y'_{lb})$  and at  $d'_{lc}$  from  $l_c$  at  $(x'_{lc}, y'_{lc})$ . Some symbols used in this study are listed in Table I.

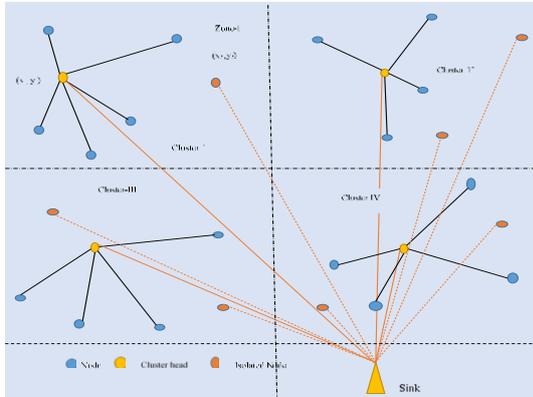


Fig. 3: Network Partitioned in 4 zones

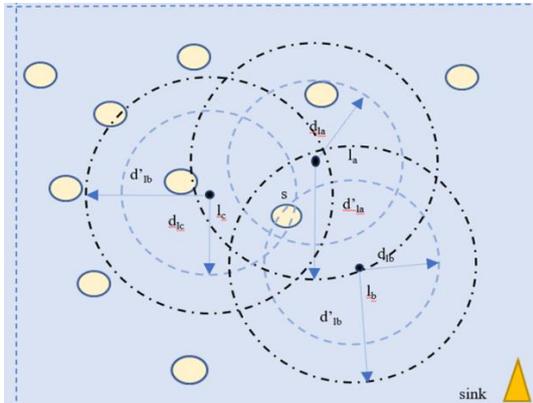


Fig. 4: Localization

Table 1: Symbols

$M$	Number of zones in network
$N \times N$	Network area
$K \times K$	Area of the individual zone
$\rho_s$	Density of nodes in zone
$nod_i$	Number of nodes in $i^{\text{th}}$ zone
$CH_i$	Cluster head of $i^{\text{th}}$ zone
$\mu$	Number of nodes in cluster
$\beta$	Number of isolated nodes
$a$	Area covered by nodes in cluster
$b$	Area covered by isolated nodes
$r$	Corona prone area
$P$	Packet size
$E_{elec}$	Energy consumed in transmitter
$E_{amp}$	Energy consumed in transmitter amplifier
$d_i$	Distance of $i^{\text{th}}$ node from cluster head
$d'_i$	Distance of $i^{\text{th}}$ isolated node from cluster head of isolated node
$d_{ISO}$	Distance of isolated node from base station (Sink)
$d'_{ISO}$	Distance of CH of isolated node from base station (Sink)
$r_{eta}$	Relative error
$r_v$	RSSI value of node

Assuming that the predicted value of distance of nodes from lantern is predicted with error. Let  $d'_{la}$ ,  $d'_{lb}$  and  $d'_{lc}$  be the predicted distances.

So the coordinates of node  $s$  ( $x_s, y_s$ ) can be estimated as -

$$\begin{aligned} \sqrt{(x_s - x'_{la})^2 + (y_s - y'_{la})^2} &\leq d'_{la} \\ \sqrt{(x_s - x'_{lb})^2 + (y_s - y'_{lb})^2} &\leq d'_{lb} \\ \sqrt{(x_s - x'_{lc})^2 + (y_s - y'_{lc})^2} &\leq d'_{lc} \end{aligned} \quad (1)$$

Now replace node 's' by the lantern nodes ' $l_a$ ' and estimating its coordinates  $(x'_{la}, y'_{la})$  by Eq. 1. Similarly obtaining  $(x'_{lb}, y'_{lb})$  and  $(x'_{lc}, y'_{lc})$ . Now relative error in desired measurement can be calculated as -

$$r_{eta} = \frac{\sqrt{(x_{la} - x'_{la})^2 + (y_{la} - y'_{la})^2}}{d_{la}} \quad (2)$$

$$\text{Where, } d_{la} = \sqrt{(x_{la} - x_s)^2 + (y_{la} - y_s)^2} \quad (3)$$

Hence, relative error in node position can be obtained. Once the coordinates of nodes are froze, it now act as lantern to enable other nodes to evaluate their positions and subsequently the position of all the sensor nodes in the network is obtained

## F. Mobile Sink

In proposed algorithm, sink moves to every zone at rendezvous point for data collection. After localization, coordinates of all the nodes in all the zones are known. Rendezvous point is selected such that it is equidistant from CH and isolated nodes as shown in fig. 8. Sink pause for predefined duration at rendezvous point and then moves to next rendezvous point in next zone.

## G. Clustering

In proposed scheme, the residual energy and ratio of distance from the center of the zone are taken into account to elect Cluster heads[3]. CH sends ping to rest of the nodes to join cluster. Once the clustering is done, isolated nodes are selected.

Now isolated nodes check whether they are in communicating range with any other isolated nodes, if yes, then they form a cluster of isolated nodes and elect CH of isolated node on basis of residual energy.

Since the nodes are randomly scattered in the network, this prompts to define the hypothesis that each zone will have non-uniform node density. For the zone of  $K \times K$  sq. Units with ' $nod_i$ ' number of nodes, density of nodes can be inferred as

$$\rho_s = \frac{nod_i}{K \times K}, \quad (4)$$

Now assuming that out of ' $nod_i$ ' number of nodes, ' $\mu$ ' number of nodes have joined cluster and ' $\beta$ ' number of nodes are left isolated. Now density can be rearticulated as,

$$\rho_s = \frac{\mu + \beta}{K \times K}. \quad (5)$$

Supposing in zone ' $i$ ', ' $a$ ' Sq. units is the area enclosed by nodes in cluster and ' $b$ ' is the area enclosed by isolated nodes such that,

$$K \times K = a + b + r \text{ squnits} \quad (6)$$

Where ' $r$ ' is the corona prone region as shown in Fig. 5.

Now all the nodes in cluster that is in area ' $a$ ' will be transmitting data packets to CH. So, energy spent in this radio transmission,

$$E_1 = \left\{ \sum_{i=1}^{\mu} (p \times E_{elec} + p \times E_{amp} \times d_i^2) \right\}, \quad (7)$$

where ‘ $d_i$ ’ is the distance of ‘ $i^{th}$ ’ node from CH. Now all the isolated nodes that is in area ‘ $b$ ’ will be transmitting data packets directly to sink. So, energy spent in this radio transmission

$$E_2 = \left\{ \sum_{i=1}^{\beta} (p \times E_{elec} + p \times E_{amp} \times d_{ISO}^2) \right\}. \quad (8)$$

Cluster head will be transmitting received packets from nodes to sink, energy spent by CH for transmitting packets to base station,

$$E_3 = (p \times E_{elec} + p \times E_{amp} \times d_{CH}^2), \quad (9)$$

So, the total energy spent by nodes in zone 1 for 1 transmission cycle

$$E = E_1 + E_2 + E_3. \quad (10)$$

According to proposed the sink should move to rendezvous point for collection of information.

Rendezvous point is selected such that it lies at equal distance from CH of isolated nodes, left over nodes and CH as shown in fig. 7 and can be evaluated as:

$$Rp = \left\{ \frac{x_{ch} + \sum_{i=1}^{\beta} x_{ISO}}{\beta + 1}; \frac{y_{ch} + \sum_{i=1}^{\beta} y_{ISO}}{\beta + 1} \right\}, \quad (11)$$

Where,  $\beta$  is left over isolated nodes.

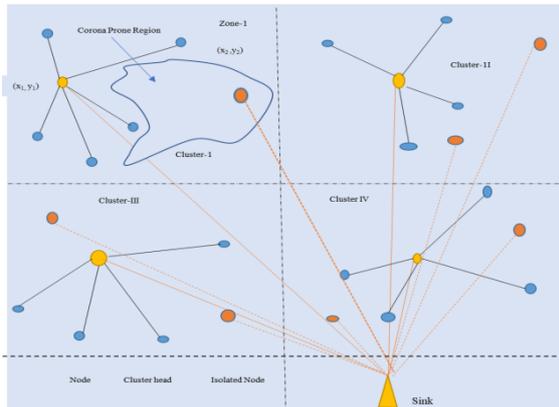


Fig 5: Clustering with Corona Prone Region

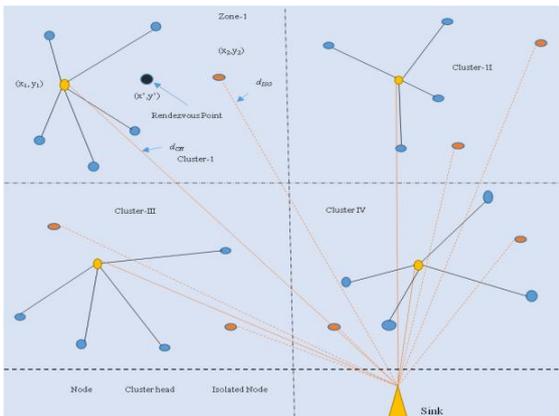


Fig. 6: Rendezvous Point

Considering the scenario, we have (i) nodes which transmit its data to CH, (ii) Cluster head, (iii) Cluster head of isolated nodes and (iv) Nodes, which were not in communication range of any another node.

Energy spent by the nodes to transfer information packets to the CH shall be the same as  $E_1$  i.e.

$$E'_1 = E_1 = \left\{ \sum_{i=1}^{\mu} (p \times E_{elec} + p \times E_{amp} \times d_i^2) \right\}, \quad (12)$$

Assuming that after clustering of isolated nodes  $\alpha$  node still remain isolated. These nodes will transmit their data packets directly to the sink. Energy exhausted by these nodes:

$$E''_2 = \left\{ \sum_{i=1}^{\alpha} (p \times E_{elec} + p \times E_{amp} \times (d'_i)^2) \right\}, \quad (13)$$

where, ‘ $d'_i$ ’ is the distance of isolated node from sink. To calculate the energy drained by isolated nodes in cluster, energy spent by isolated nodes to transfer data to CH of isolated nodes:

$$E''_2 = \left\{ \sum_{i=1}^{\beta-\alpha-1} (p \times E_{elec} + p \times E_{amp} \times (d'_i)^2) \right\}, \quad (14)$$

where ‘ $d'_i$ ’ is distance of ‘ $i^{th}$ ’ isolated node from CH of isolated node.

Energy exhausted by CH of isolated node to transfer data packets to sink can be calculated as:

$$E'_2 = (p \times E_{elec} + p \times E_{amp} \times (d'_{ISO})^2), \quad (15)$$

Finally, the energy drained by CH in proposed scheme to transfer information to mobile sink,

$$E'_3 = (p \times E_{elec} + p \times E_{amp} \times (d'_{CHR})^2), \quad (16)$$

Now the total energy saved

$$E_{saved} = E_1 + E_2 + E_3 - E'_1 - (E'_2 + E''_2 + E''_2) - E'_3, \quad (17)$$

$$E_{saved} = E_1 - E'_1 + E_2 - (E'_2 + E''_2 + E''_2) + E_3 - E'_3$$

From equation 12 we have,  $E_1 = E'_1$ . So, equation 17 reduces to :

$$E_{saved} = E_2 - (E'_2 + E''_2 + E''_2) + E_3 - E'_3 \quad (18)$$

Putting the values of  $E_2, E_3$  and  $E'_2, E''_2, E'_3,$

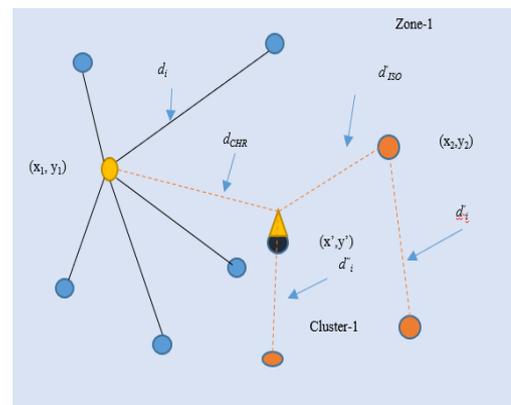


Fig. 7: Proposed scenario for zone-1 Isolated Node

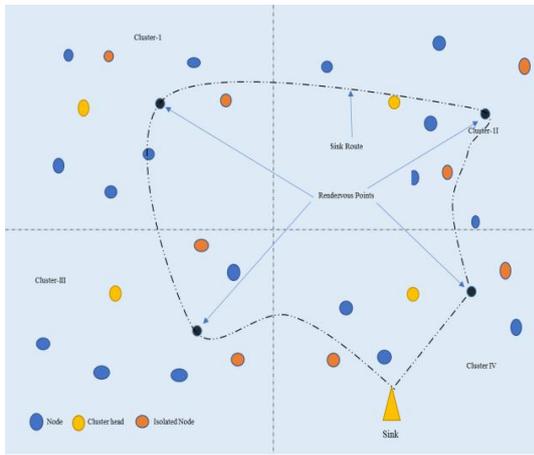


Fig. 8: Proposed scenario with rendezvous points

$$E_{saved} = \left\{ \sum_{i=1}^{\beta} (p \times E_{elec} + p \times E_{amp} \times d_{ISO}^2) \right\} - \left\{ \sum_{i=1}^{\beta-\alpha-1} (p \times E_{elec} + p \times E_{amp} \times (d'_i)^2) + \sum_{i=1}^{\alpha} (p \times E_{elec} + p \times E_{amp} \times (d'_i)^2) \right\} + (p \times E_{elec} + p \times E_{amp} \times d_{CH}^2) - (p \times E_{elec} + p \times E_{amp} \times (d'_{CHR})^2) \quad (19)$$

Assuming,  $d_{ISO} \sim d'_i \sim d''_i = d_{ISO}$ , for sake of simplicity in analysis, we have,

$$E_{saved} = \left\{ \sum_{i=1}^{\beta} (p \times E_{elec} + p \times E_{amp} \times d_{ISO}^2) \right\} - \left\{ \sum_{i=1}^{\beta} (p \times E_{elec} + p \times E_{amp} \times (d'_{ISO})^2) + p \times E_{amp} (d_{CH}^2 - d'^2_{CHR}) \right\} \quad (20)$$

$$E_{saved} = p \times E_{amp} \times \left\{ \sum_{i=1}^{\beta} (d_{ISO}^2 - d'^2_{ISO}) + (d_{CH}^2 - d'^2_{CHR}) \right\} \quad (21)$$

It is obvious that  $(d_{ISO} \square d'_{ISO}) \& (d_{CH} \square d'_{CHR})$

$$\text{Therefore, } E_{saved} \cong p \times E_{amp} \times \left\{ \sum_{i=1}^{\beta} (d_{ISO}^2) + (d_{CH}^2) \right\} \quad (22)$$

For every rotund new cluster head is designated, isolated nodes are recognized, and contingent on this information, new location for mobile BS is designated. Base Station moves from zone to zone for collecting data from rendezvous point (Fig.8) reducing energy consumption of the Cluster Head and Isolated nodes.

The duration for which mobile base station stays in every zone is predefined to make communication between nodes more effective. This entire algorithm saves the energy of the nodes, which have highest probability to drain their energy and create coronas in the network. Hence, networks life is augmented.

## H. Algorithm for clustering in ORP-MS

```

for j=1:M
for i=1: nodi
    if R.E.(nodi)==highest
set status as CH
    else
set status Cluster member
    end
end
end
for each CHi ∈ CH do
CHi broadcast ADV message to its neighbors
end
for each nodk ∈ Ndo
if Adv. message = received from CHi ∈ CH
nodk becomes part of the connected set

```

```

CoNSet[con]= nodk
con++
else
nodk becomes part of unconnected set
UnCoNSet [uncon]= nodk
uncon++
end
end
for each nodk do
    if nodk ∈ CoNSet
        Compute RSSI -> CHi
        RSSI val[rv]=RSSI - >CHi
rv++
    end
Cluster[μ]=Min { RSSI val[rv] }
μ++
    if Sensor node ∈ UnCoNSet
if Dist(nod(k)->nod(k+1)) < R
send ISO_Join message to form cluster
    end
    end
if ISO_Join message = received
Update CoNSet: CoNSet[con]= nodk
Con++
Update UnCoNSet: UnCoNSet[uncon]- nodk
uncon--
    else
IsoSet[β]= nodk
β++
    end
end
end
Compute Rendezvous points in each zone
Rp={Rp1,Rp2,...,Rpm}
CH Distribute TDMA schedule to the cluster members
Start data collection tour
for each point in Rp
Move to rendezvous point in tandem.
Collect data
end

```

## 4. Simulation Results

We have evaluated the performance of ORP-MS with existing algorithm DECA [22], EEHC [32] and ES-WCA [27] by coding using MATLAB 2017a. The experimental scenario parameters are listed in Table II.

Performance comparison of ORP-MS and existing algorithms are as follows:

### A. Number of Active Sensors and Active Cluster Heads

Fig. 9 and 10 show number of active cluster heads and number of active nodes per round respectively for entire simulation duration. Fig. 9 reflects the number of active CHs per round. Due to static sink approach and single hop communication CH in EEHC drain energy quickly. However, DECA, ES-WCA and ORP-MS show improvement due to mobile sink approach. Furthermore, as the isolated nodes are also being clustered and rendezvous point is selected for every round ORP-MS shows bodacious improvement over previous schemes.

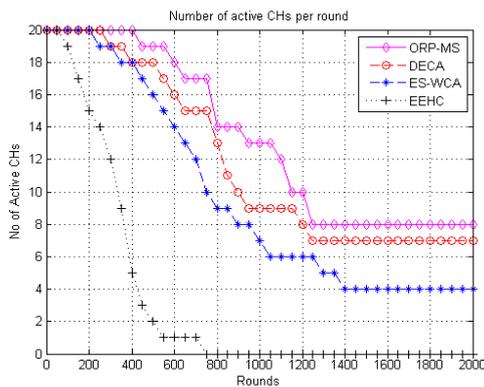
Fig. 10 shows the number of active sensors per round. It is clear that in DECA and ORP-MS all the sensors are active since starting owing to the fact that both the schemes bind unconnected sensors as well. Further, we see considerable improvement in ORP-MS scheme, as all the sensors are active for more than around 1200<sup>th</sup> round. Fig. 10 clearly indicates that the more nodes are alive for longer number of rounds that means network life is prolonged using ORP-MS approach.

### B. Remaining Energy

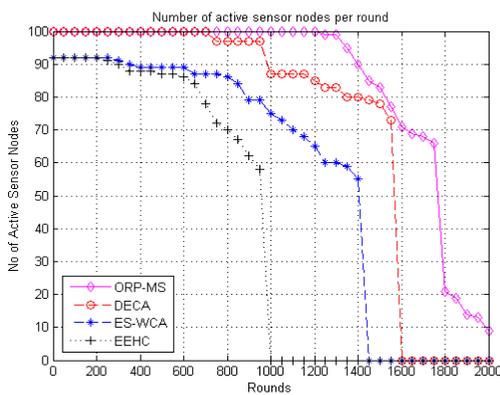
Fig. 11 shows the average remaining energy of entire network. This graph has a gradual downwards slope indicating uniform energy consumption in the network which further depicts the efficient and well-balanced consumption of Proposed ORP-MS algorithm.

**Table 2:** Network parameters

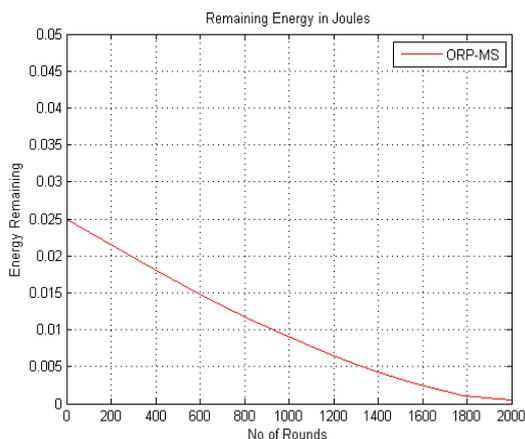
Radius of Target area	50 m
No. of sensors	100
No. of CHs	15-30
Initial energy of sensors	.02 J
Initial energy of sensors	.1J
T <sup>x</sup> range of sensors	10m
Size of Control packet	100bits
Size of Data packet	500bits
Multi-path fading	.0013 pJ/bit/m4
T <sup>x</sup> or R <sup>x</sup> electronics	50nJ/m2/bit



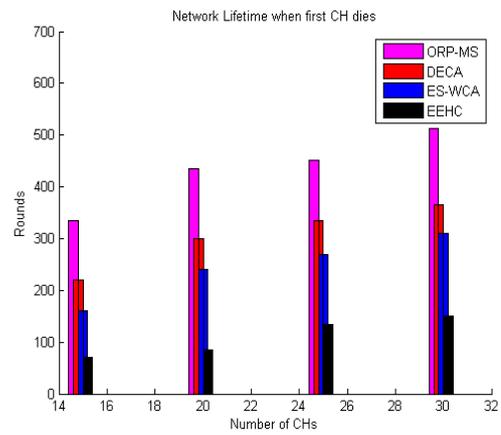
**Fig. 9:** Number of active CH per round



**Fig. 10:** Number of active nodes per round



**Fig. 11:** Remaining energy in Joules



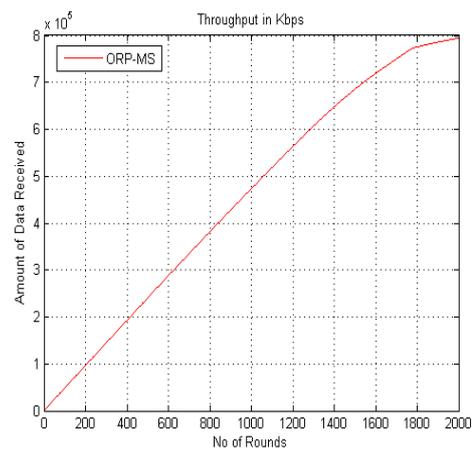
**Fig. 12:** Network lifetime

### C. Network lifetime

In Fig. 12, network lifetime is evaluated of the WSNs by Changing the number of zones thereby changing number CHs in the network from 15-30. The benchmark of lifetime is assigned on the round at which the first CH dies. From Fig. 12, we can observe that ORP-MS has outperformed the existing algorithms in terms of networks lifetime.

### D. Throughput

Fig. 13 depicts deployed scenario. It is bodacious that as the network reaches around 1800<sup>th</sup> round, only 20 nodes are found to be alive in the network. This means that further increase in the throughput would be less gradual as equated with the earlier rounds. And after the 2000<sup>th</sup> round, the value of throughput becomes constant indicating that nodes have practically died out and no further communication is happening in the network.



**Fig. 13:** Throughput (summation of subsequent rounds)

## 5. Conclusion

In this work, a new clustering algorithm using mobile sink with varying rendezvous point is proposed named Optimal Rendezvous Point Selection using Mobile Sink (ORP-MS). The proposed algorithm makes sure minimum isolated nodes and variable rendezvous point that minimum energy is drained in transmitting information to the sink. For every round rendezvous point is selected such that it approximately lies in mid of CH, CH of isolated nodes and leftover node if any, as shown in Fig. 7. The simulation result proves that ORP-MS has an edge over other existing schemes; viz. DECA, EEHC and ES-WCA. The substantial improvement was seen terms of network lifetime, energy efficiency and high throughput is achieved.

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