The Synthesis of Agar Silicone Biocomposite and Its Mechanical Properties

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Abstract

Silicone rubber is widely used in the medical field, whereas agar is widely used as a medium to breed bacteria or to carry the active ingredient for a specific purpose. There are few synthetic skins available in the market that are made of silicone, such as Biobrane, Integra and Transcyte, to name a few. Meanwhile, in a previous study, agar is used to carry the active ingredients in turmeric to the wounded skin and expedite its recovery. However, up to date, there is no available skin substitute with the ability for carrying bioactive ingredient that would expedite wound healing and anti-bacterial properties. Hence, this study aims to synthesise a new biocomposite that could mimic skin mechanical properties with the future potential to carry bioactive ingredient via agar particles. The material constants for this newly developed agar slicone biocomposite are determined using Neo- Hookean, Mooney-Rivlin and Ogden models. This research consists of two main stages; which is the synthesis and the determination of the mechanical properties of agar silicone biocomposite, via experimental and numerical approach. The experimental approach involves testing the biocomposite under uniaxial tensile test, while the numerical approach involves curve fitting method using a Matlab programme. The calculated parameter for Neo-Hookean (C1) ranges from 52-57 kPa for all variances of agar silicone biocomposite. As for Mooney-Rivlin, the values are of 34-38 kPa and 47- 54 kPa for C1 and C2 re spectively. Ogden parameters (Ogden coefficient, μ and Ogden exponent, α) for agar silicone biocomposites are 48-54 kPa; 2.17-2.19 (μ;α). The material constants of agar silicone biocomposites lays within the range of human tissue and skin, as well as animal skin; thus proving that agar silicone biocomposite could deform nearly the same as skin. Therefore, it can be concluded that this study has significant contribution to better understand the mechanical properties of the newly developed agar silicone biocomposite.

Keywords: synthesise; silicone rubber; biocomposite; agar; silicone

1. Introduction

Silicone rubber or polysiloxanes or polydimethylsiloxane is categorised as a synthetic polymer [1,2]. It comprises of Si-O backbone bonded with organic groups (R) and behaves like a natural rubber. Polydimethylsiloxanes which are also abbreviated as PDMS is the most used silicone rubber and also the foundation of all silicone. Silicone is used in contact lenses since 1998, since it allows oxygen permeability into the eye, compared to the conventional hydrogel contact lenses [3]. A study by Jinping Hou uses nylon and silicone rubber (Ecoflex 0030), to imitate the deformation of octopus skin, for an octopus inspired robot [4]. The results, however, showed a smaller deformation compared to the real octopus skin. Silicone is also gaining popularity in the medical field as aesthetic implants (testical implant, breast implant and nose implant), orthopaedic implants (the socket in hip joint, finger joint), medical disposable supplies (needle, syringe, catheter, extracorporeal equipment, shunt, drains and tubes), and dental implants. Besides that, silicone is also used as one of the main substance in synthetic skin substitutes , such as Biobrane®, Integra® and TransCyte®. The synthetic skins are grouped into two categories:1) according to the time it is used (temporary or permanent skin substitutes) and 2) according to the type of material used (biological or synthetic skin substitutes).

Agar is composed of alternating 1,3-linked-D –galactose and 1,4-linked 3,6-anhydro-L-galactose units. It is easily accessible, and been used extensively in the food industry, as it has high gelling ability[5]. In a study by [6], the film prepared from agar alone have low tensile strength, brittle, as well as being sticky and difficult to handle, whilst film prepared from agar and gelatin is non-sticky, but very stiff. The value of the tensile strength for agar-gelatin film was not mentioned in the paper. Thus, the agar- based control film in the study consist of agar-gelatin-glycerol-propylene glycol (AGGP), where glycerol and propylene glycol act as the plasticizers to the polymeric film. Plasticizers are added to the agar-gelatin film to reduce its brittleness, since it works as spacers between the polymeric chain and increases its flexibility and extensibility of polymers.The turmeric extracts were then impregnated into the AGGP film. Turmeric was used extensively as medicine in earlier days, as it has antimicrobial, antioxidant and wound healing properties [6]. The turmeric extract in [6] provides suitable microenvironment to the wound, where it was observed that it has lesser bacterial growth (compared to the control film) and accelerates the healing process.

However, to date, there is no available skin substitute with the ability for carrying bioactive ingredient that would expedite wound healing and anti-bacterial properties.

Hence, this study aims to synthesise a new biocomposite that could mimic skin mechanical properties with the future potential to carry bioactive ingredient via agar particles. The material constants for this newly developed agar slicone biocomposite are determined using Neo- Hookean, Mooney-Rivlin and Ogden models. This is novel as the mechanical properties of agar silicone bicomposite have not been reported before.

2. Materials and Method

This research consists of two main steps in order to obtain the material constant of agar silicone biocomposite, which were the synthesis process and the determination of the material constants. In order to determine the material constants; two approaches are used; 1) experimental approach (which is the uniaxial tensile test) and 2) numerical approach. Numerical approach was used because the raw data from tensile test alone could not determine the material constants of agar silicone biocomposites. The mechanical properties of this biocomposite is the material constant parameters in the hyperelastic constitutive models. Figure 1 shows the overall flow of the processes involved in this study.
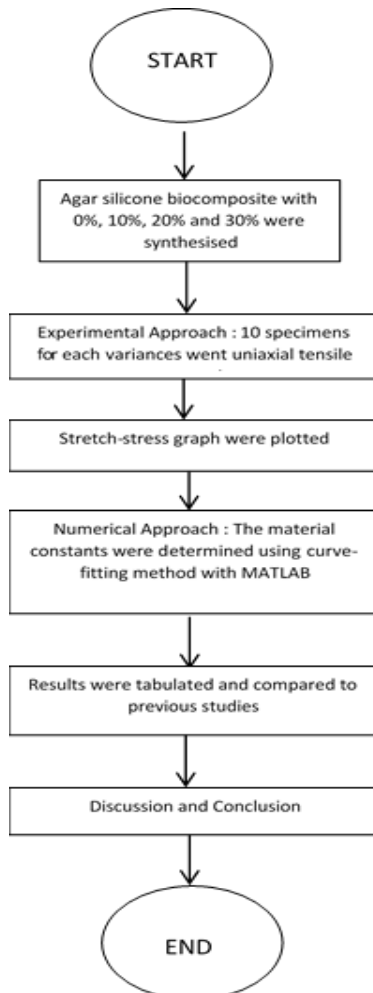

Fig 1 : The overall flow of the processes involved in this study.

The materials that were used in this research were agar powder and platinum cured soft silicone Ecoflex 0030. Silicone Ecoflex 0030 were obtained from the sole distributor of Smooth-On in Malaysia, Castmech Sdn Bhd. Silicone Ecoflex came in liquid form with two parts; Part A and B. Both parts were mixed with the

ratio of 1A:1B. After mixing,the silicone was poured into the beaker that contains agar powder.

Agar powder was obtained from a local grocery store. The amount of agar needed for each biocomposite variances were calculated. The desired weight of agar powder for 10, 20 and 30% variances were 0.7 g, 1.4 g and 2.1 g respectively.

The agar and silicone mixture were mixed and stirred using a spatula. The stirring process was essential to ensure the final product to be homogenous. Secondly, the bubbles in the mixture was removed using MCP vacuum casting system machine, before pouring it into the aluminium mold. Lastly, the agar silicone in the mold was cured in the oven at 73°C. The same process was repeated until ten specimens were obtained for each variance. Figures 2-1 till 2-4 show the step by step sample preparation.

2-1. Stirring process of agar silicone biocomposite

2-2. Bubble removal using vacuum casting system

2-3. Pouring the mixture into the mold

2-4.Curing process in the oven

Then, the agar silicone biocomposite underwent uniaxial tensile testing. The biocomposite were assumed to be hyperleastic, incompressible and isotropic. Equations 1, 2 and 3 were hyperelastic equations for incompressible and isotropic materials in terms of elastic strain density function, *W*. Equation 1 is the Neo-Hookean model, equation 2 is Mooney-Rivlin model and equation 3 is Ogden model.

However, the raw data obtained from the uniaxial tensile test were engineering stress-strain (σ_E–ε). Thus, equations 1, 2 and 3 were manipulated to yield the engineering stress σ_E and stretch, λ equations (equations 4, 5 and 6 respectively) in order to simplify the calculations. The values of stretch, λ can be calculated from the strain values [13] and the engineering stress-stretch graphs were plotted. These curves are known as the reference curves.

The next step was the curve fitting procedure using equations 4, 5, and 6 to get the best match curve to the reference curve. This best match curve will give the value of the material constants parameters in the equations. The material constants are C1 for Neo-Hookean (1 and 4), C1 and C2 for Mooney-Rivlin (2 and 5) and α and μ for Ogden (3 and 6). These material constants represent the mathematical parameters in the equations of the hyperelastic models which describes the mechanical behaviour of the biocomposites.

$$W = C_1 (I_1-3) \tag{1}$$

$$W = C_1 (I_1-3)+ C_2 (I_2-3) \tag{2}$$

$$W = \sum_{i=1}^{N} \frac{\mu_i}{\alpha_i} \left(\lambda_1^{\alpha_i} + \lambda_2^{\alpha_i} + \lambda_3^{\alpha_i} - 3 \right) \tag{3}$$

Equations (4), (5) and (6) below show the engineering stress, σ_E as a function of stretch, λ, which are the simplifications of equations 1, 2 and 3.

$$\sigma_E = (2C_1)\left(\lambda - \frac{1}{\lambda^2}\right) \tag{4}$$

$$\sigma_E = \frac{1}{\lambda}\left[\left(2C_1 + \frac{2C_2}{\lambda}\right)\left(\lambda^2 - \frac{1}{\lambda}\right)\right] \tag{5}$$

$$\sigma_E = \frac{\mu}{\lambda}\left(\lambda^\alpha - \lambda^{-\alpha/2}\right) \tag{6}$$

3. Results and Discussion

After obtaining the material constants from the curve fitting procedure, the results were tabulated. Table 3.1 shows the value of the material constants for all three hyperelastic constitutive models, Neo-Hookean, Mooney Rivlin and Ogden. The results show that the value of the material constant increases as the reinforcement material increases. This is true for all the three constitutive models in agar silicone biocomposite. Another observation that can be made is the decreasing tensile strength of the biocomposite as the reinforcement material increases. These are shown in Fig 3.1 to Fig 3.3 where the stress to fail decreases slightly as the filler of the biocomposite increases. This is due to the presence of the weak adhesive bond between the matrix and its filler. The drying process of the silicone biocomposite in the oven at 73°C has reduces the moisture in the silicone biocomposite, hence reducing the stretchiness of the material.

Table 3.1: The material constants for all specimens

Variances		Material Constants (MPa)		
		Neo-Hookean	Mooney-Rivlin	Ogden
Agar silicone	0%	C1=0.028	C1=0.033 C2=0.005	α= 2.170 μ=0.046MPa
	10%	C1=0.052	C1=0.034 C2=0.047	α= 2.450 μ=0.046MPa
	20%	C1=0.053	C1=0.035 C2=0.048	α= 2.452 μ=0.049MPa
	30%	C1=0.057	C1=0.038 C2=0.054	α= 2.588 μ=0.049MPa

Fig 3.1 shows the stress stretch relationship of agar silicone biocomposite that adapts Neo-Hookean model.
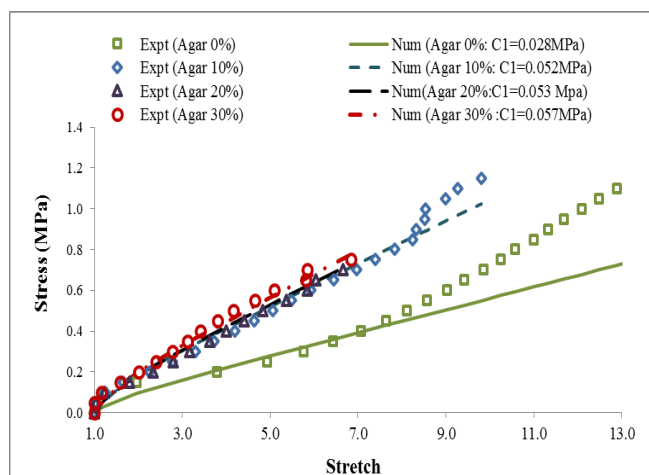

Fig 3.1: The stress stretch relationship of agar silicone biocomposite adapting Neo-Hookean model.

Fig 3.2 is the stress stretch relationship of agar silicone bioomposite that adapts Mooney-Rivlin model. Both values of C1 and C2 increases as the reinforcement material increases. The stress stretch lines were farther from the experimental stress stretch lines.
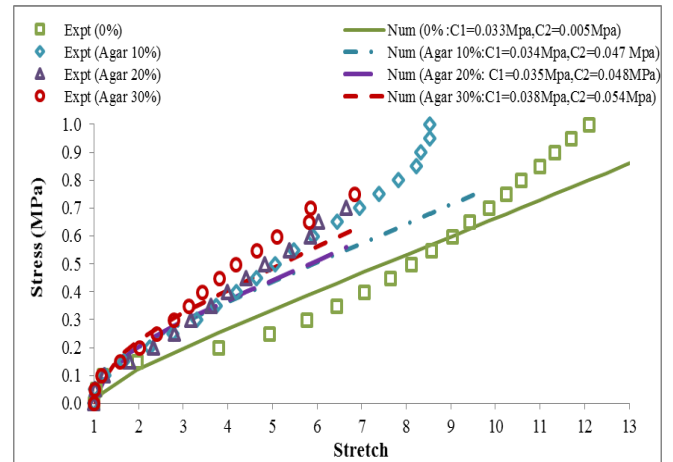

Fig 3.2: The stress stretch relationship of agar silicone biocomposite adapting Mooney Rivlin model

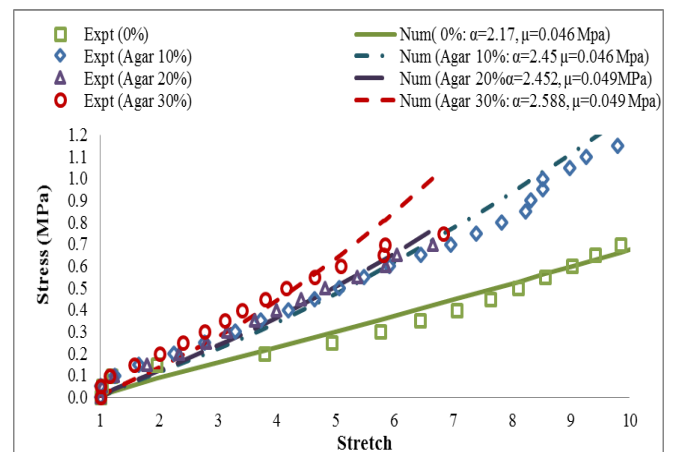Figure 3.3 shows the stress stretch relationship of agar silicone biocomposite that adapts Ogden model.

Fig 3.3: The stress stretch relationship of agar silicone biocomposite adapting Ogden model

Figure 3.4 and Figure 3.5 show the numerical method graphs using the material constants for all three hyperelastic constitutive models, Neo-Hookean, Mooney Rivlin and Ogden relative to the experimental method. These two graphs indicate that Mooney-Rivlin and Neo-Hookean constitutive model best describes the hyperelastic properties of agar silicone biocomposite.
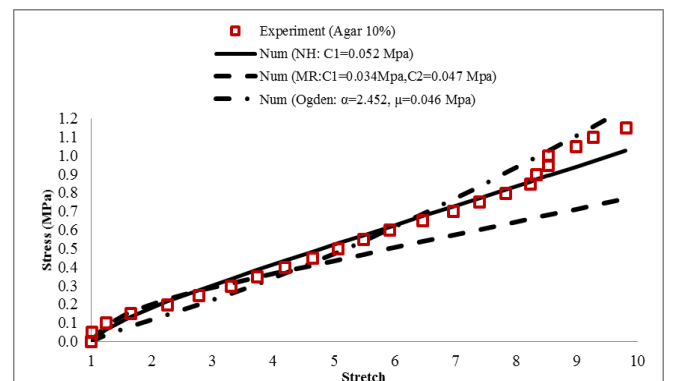

Fig 3.4: The stress stretch relationship of 10% agar silicone biocomposite adapting Neo-Hookean, Mooney-Rivlin and Ogden model.
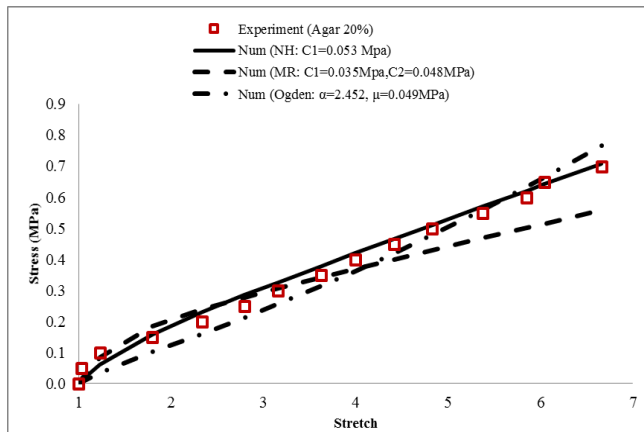
Fig 3.5: The stress stretch relationship of 20% agar silicone biocomposite adapting Neo-Hookean, Mooney-Rivlin and Ogden model.

A study on chloropene rubber showed that Mooney-Rivlin and Ogden model best described the material in a specific ranges for isotropic hyperelastic model [17]. Ogden model are more complex and thus more suitable for large deformations, compared to Mooney-Rivlin. Both Mooney-Rivlin and Neo-Hookean are more suitable for a simple check in small strain range.

Table 3.2 until Table 3.4 compare the results obtained from this study to the previous findings under uniaxial tensile test. Table 3.2 illustrates the comparison of the material constants that adapts the Neo-Hookean model (C1) from previous studies to the current research. Meanwhile, Table 3.3 depicts the comparison of former study that adapts the Mooney-Rivlin model to this research. Lastly, Table 3.4 is the comparison of Ogden material properties (µ and α) of soft tissues and other hyperelastic materials under tensile test. From these three tables, the determined parameter for Neo-Hookean (C1) ranges from 52-57 kPa for agar silicone biocomposite. As for Mooney-Rivlin, the parameters for agar silicone has the value of 34-38 kPa and 47- 54 kPa for C1 and C2 respectively. Ogden parameters (Ogden coefficient, µ and Ogden exponent, α) for agar silicone are 48-54 kPa; 2.17-2.19 (µ;α). The material constant increases with the increase of reinforcement material. Agar silicone biocomposites are softer than fresh animal skin such as bovine and goat (as the value of the material constants are lower), but the values are in between the material constants of orbital fat and connective tissue (OFCT) of the eye and human skin in tension.

There are studies by Mahmud, L., *et al.*, and Mahmud, J. *et al.*, on human skin using finite element method to obtain Ogden parameters [8,9]. The studies concluded that the value for µ = 26 Pa, α =110 and µ = 10 Pa, α =40 respectively. Both studies showed a lower value of Ogden shear modulus compared to agar silicone biocomposite.

Table 3.2: Comparison of Neo-Hookean material properties from previous study to this research

C_1	Specimen	Test Type	Reference
5 kPa	Pulmonary Artery Tissue	Tension	[10]
0.8 to 1.7 kPa 2.1 to 3.5 kPa	Human Orbital Fat & Connective Tissue in eye (OFCT)	Tension	[11]
2.1 to 3.5 kPa	Porcine Orbital Fat & Connective Tissue in eye (OFCT)	Tension	[11]
52 to 57 kPa	Agar silicone Biocomposites	Uniaxial tension	CURRENT STUDY
123.8 to 142.1 kPa	Elastin	Tension	[12]
0.651-1 MPa	Thin Polymer Layers	Tension	[13]
3.98 -4.58 MPa	Fresh goat skin unshaved	Tension	[14]
6.81-8.51 MPa	Fresh goat skin shaved	Tension	[14]
14.23-24.67 MPa	Goat Leather	Tension	[14]
21.88 MPa	Bovine Leather	Tension	[14]

Table 3.3: Comparison of Mooney-Rivlin material properties from previous study to this research

C_1	C_2	Specimen	Test Types	Reference
-11.2 to -7.1 kPa	10.1 to 16.1 kPa	Porcine Orbital Fat & Connective Tissue in eye(OFCT)	Tension	[11]
-5.0 to -2.7 kPa	3.8 to 7.1 kPa	Human Orbital Fat & Connective Tissue in eye(OFCT)	Tension	[11]
17.97 kPa	11.3 kPa	Nylon+silicone (Ecoflex)	Tension	[4]
34 to 38 kPa	47 to 54 kPa	Agar silicone Biocomposites	Uniaxial Tension	CURRENT STUDY
0.3 MPa	0 MPa	Human Skin	Tension	[13]
0.5 MPa	0 MPa	Silicone Rubber (B452)	Tension	[13]
1.0 MPa	0.9 MPa	Silicone Rubber (Sil8800)	Tension	[11]
74.51 to 96.57 MPa	-88.61 to -109.24 MPa	Fresh goat skin shaved	Uniaxial Tension	[14]

Table 3.4: Comparison of Ogden material properties from previous study to this research

Shear Modulus, µ	Strain hardening component, α	Specimen	Test Type	Reference
10 Pa	110	Human Skin (ventral forearm)	Tension	[15]
48 to 54 kPa	2.169 to 2.185	Agar silicone Biocomposites	Uniaxial Tension	CURRENT STUDY
0.11 MPa	9	Human Skin	Uniaxial Tension	[16]
0.153 to 0.18 MPa	15.15 to 18.34	Fresh goat skin unshaved	Uniaxial Tension	[14]
0.152 to 0.277 MPa	16.16 to 17.31	Fresh goat skin shaved	Uniaxial Tension	[14]
1.827 MPa	15.89	Goat leather	Uniaxial tension	[14]
3.50 MPa	14.82	Bovine leather	Uniaxial tension	[14]

4. Conclusions

In conclusion, this research has succesfully shown the synthesising process of the newly developed agar silicone biocomposite and determined its Neo-Hookean, Mooney-Rivlin and Ogden material constants and coefficients respectively. This is novel as the mechanical properties of agar silicone biocomposite have not been reported earlier. It is interesting to find that the material constants of agar silicone biocomposites lays within the range of human tissue and skin, as well as animal skin. This proves that agar silicone biocomposite could deform nearly the same as skin. This study will lead to the development of a new synthetic skin with the ability to carry bioactive ingredients for would healing application.

Acknowledgement

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